

Analytical expression of Complex Riemann Xi function $\xi(s)$ and proof of Riemann Hypothesis.

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Abstract:

[In this paper explicit analytical expression for Riemann Xi function $\xi(s)$ is worked out for complex values of s . From this expression Riemann Hypothesis is proved. Analytic Expression for non-trivial Zeros of Riemann Zeta function $\zeta(s)$ is also found. Two more proofs of Riemann Hypothesis are also given.]

Keywords : Riemann Zeta and Riemann Xi function, Riemann Hypothesis, Critical line, non-trivial zeros.

1. Introduction:

One of the most difficult problems today to mathematicians and physicists is Riemann Hypothesis. It is a conjecture proposed by Bernhard Riemann which says that all the complex zeros of Riemann Zeta function $\zeta(s)$ has real part $\sigma = \frac{1}{2}$. Till now this conjecture is neither proved nor disproved. In this paper an explicit analytical expression of Riemann Xi function $\xi(s)$ is found. From this expression of $\xi(s)$ expression for zeros of $\xi(s)$ is derived. As it is known that all the zeros of $\xi(s)$ are identical with nontrivial zeros of Riemann zeta function, the zeros of $\xi(s)$ are identified as nontrivial zeros of Riemann zeta function $\zeta(s)$.

The paper is organized as follows. In section 2, we summarize the definition of Riemann Xi and Riemann zeta function, mention the connection between $\xi(s)$ and $\zeta(s)$. We also mention some important results related to zeros of $\zeta(s)$. Next in section 3, the expression for $\xi(s)$ in terms of an arbitrary function is derived. In section 4, the analytical expression for $\xi(s)$ is worked out using a theorem of analysis. In section 5, Riemann Hypothesis is proved and equation for nontrivial zeros of $\zeta(s)$ is derived. In Section 6, a second proof of Riemann Hypothesis is given. In section 7, a third proof of Riemann Hypothesis is given. Section 8 contains conclusion and comments. An appendix is added after section 8.

2. Riemann zeta and Xi function and Riemann Hypothesis

For real $s > 1$, Riemann zeta function $\zeta(s)$ is defined as [1, 2, 3]

$$\zeta(s) = \sum_{v=1}^{\infty} v^{-s} \quad \dots (2.1)$$

The definite integral equivalent of (2.1) is

$$\Gamma(s) \zeta(s) = \int_0^{\infty} \frac{t^{s-1}}{e^t - 1} dt ; \quad \text{real } s > 1 \quad \dots(2.2)$$

and $\Gamma(s) \equiv$ Gamma function

$\zeta(s)$ can be analytically continued from (2.1) and can be defined for $0 < \text{real } s < 1$

$$\Gamma(s) \zeta(s) = \int_0^{\infty} \left(\frac{1}{e^t - 1} - \frac{1}{t} \right) t^{s-1} dt ; \quad 0 < \text{real } s < 1 \quad \dots (2.3)$$

Riemann zeta function satisfies a well-known functional equation [3] :

$$\pi^{-\frac{s}{2}} \Gamma(s/2) \zeta(s) = \pi^{-\left(\frac{1-s}{2}\right)} \Gamma\left(\frac{1-s}{2}\right) \zeta(1-s) \quad \dots (2.4)$$

This functional equation (2.4) is also a definition of $\zeta(s)$ over whole complex s -plane except a singularity at $s = 1$.

A consequence of symmetry of (2.4) suggests that if there is a complex zero of $\zeta(s)$ for $\text{Re } s = \frac{1}{2} + \delta$, then there must be another zero of $\zeta(s)$ for $\text{Re } s = \frac{1}{2} - \delta$.

Riemann introduced another function known as Riemann Xi function $\xi(s)$ which satisfies a functional equation :

$$\xi(s) = \xi(1-s) \quad \dots (2.5)$$

The Riemann Xi and Riemann zeta function are connected through the equation [1] :

$$\xi(s) = \frac{1}{2} s(s-1) \pi^{-\frac{s}{2}} \Gamma(s/2) \zeta(s) \quad \dots (2.6)$$

The Riemann zeta function has real and complex zeros [2]. The real zeros of $\zeta(s)$ are known as trivial zeros and are given by

$$\zeta(-2m) = 0 ; \quad m = 1, 2, 3, \dots \dots \dots \quad \dots (2.7)$$

The complex zeros of $\zeta(s)$ lie [1] within the strip $0 < \text{Re } s < 1$. This strip is known as critical strip and zeros lying in critical strip are known as nontrivial zeros. And the straight line $\text{Re } s = \frac{1}{2}$ is called critical line .

Now a consequence of (2.6) is that the nontrivial zeros of Riemann zeta function $\zeta(s)$ are identical with zeros of Riemann Xi function $\xi(s)$ [3].

Riemann Hypothesis is a conjecture made by Riemann which says that the nontrivial zeros of Riemann zeta function $\zeta(s)$ has real part $\sigma = \frac{1}{2}$. This implies that the zeros of Riemann Xi function $\xi(s)$ has also real part of $\sigma = \frac{1}{2}$. This Hypothesis has not yet been proved or disproved.

The literatures on $\xi(s)$ and $\zeta(s)$ are extremely large. Only a few important results related to zeros of $\zeta(s)$ are mentioned. G. H. Hardy [4] has proved that an infinite number of zeros lie on the critical line $\sigma = \frac{1}{2}$. J. B. Conrey [5] has shown that more than 40% zeros of $\zeta(s)$ lie on critical line. N. Levinson [6] has shown that more than one-third zeros of $\zeta(s)$ lie on critical line.

3. Expression of Riemann Xi function $\xi(s)$ in terms of an arbitrary function.

As the nontrivial zeros of $\zeta(s)$ are identical with zeros of $\xi(s)$, we will consider $\xi(s)$ and find its analytical expression in terms of an arbitrary function. This is more convenient which will be clear later.

Firstly, we will consider solution of (2.5) which is satisfied by $\xi(s)$. The solution of (2.5) in terms of an arbitrary function was given by Hymer [7]. Following Hymer [7] the general solution of the equation (2.5) can be written as in terms of an arbitrary function.

Hymer considers the functional equation of more general form

$$\varphi(a + bs) = n\varphi(s); \quad n, a, b \text{ are constants} \quad \dots(3.1)$$

and gives the solution of (3.1) as

$$\varphi(s) = \left(C_0 s - \frac{C_0 a}{1-b}\right)^{\frac{\log n}{\log b}} \theta_0 \left[\text{Cos} \left\{ \frac{2\pi}{\log b} \cdot \log \left(C_0 s - \frac{C_0 a}{1-b} \right) \right\} \right] \quad \dots(3.2)$$

$C_0 \equiv$ arbitrary constant
 $\theta_0 \equiv$ arbitrary function

Now for $a = 1, b = -1$ and $n = 1$ equation (3.1) reduces to

$$\varphi(1 - s) = \varphi(s) \quad \dots(3.3)$$

Equation (2.5) and (3.3) are of same form. Hence solution of (2.5) and (3.3) will have identical form.

The solution of (3.3) in terms of an arbitrary function θ_0 follows from (3.2) :

$$\begin{aligned} \varphi(s) &= \left(s - \frac{1}{2}\right)^{\frac{\log 1}{\log(-1)}} \theta_0 \left[\text{Cos} \left\{ \frac{2\pi}{\log(-1)} \cdot \log \left(s - \frac{1}{2} \right) \right\} \right] \\ &\quad \text{taking } C_0 = 1 \text{ in (3.2)} \\ \text{i.e., } \varphi(s) &= \left(s - \frac{1}{2}\right)^{\frac{2n\pi i}{(2n+1)\pi i}} \theta_0 \left[\text{Cos} \left\{ \frac{2\pi}{\log(-1)} \cdot \log \left(s - \frac{1}{2} \right) \right\} \right] \\ &= \left(s - \frac{1}{2}\right)^{\frac{2n}{(2n+1)}} \theta_0 \left[\text{Cos} \left\{ \frac{2\pi}{(2n+1)\pi i} \cdot \log \left(s - \frac{1}{2} \right) \right\} \right] \\ &= \left(s - \frac{1}{2}\right)^{\frac{2n}{(2n+1)}} \theta_0 \left[\text{Cos} \left\{ \frac{-2i}{(2n+1)} \cdot \log \left(s - \frac{1}{2} \right) \right\} \right] \\ &= \left(s - \frac{1}{2}\right)^{\frac{2n}{(2n+1)}} \theta_0 \left[\text{Cosh} \left\{ \frac{2}{(2n+1)} \cdot \log \left(s - \frac{1}{2} \right) \right\} \right] \quad \dots(3.4) \end{aligned}$$

A glance at (3.4) suggests that $\varphi(s)$ can be written more conveniently in terms of another arbitrary function.

$$\text{Therefore } \varphi(s) = \psi_0(s - 1/2) \quad \dots(3.5)$$

$\psi_0(s - 1/2)$ is another arbitrary function.

Now comparing (2.5), (3.3) and (3.5) we can write the solution of (2.5) in terms of an arbitrary function :

$$\xi(s) = \psi(s - 1/2) \quad \dots(3.6)$$

Equation (3.6) is the solution of (2.5) and represents the Riemann Xi function $\xi(s)$ in terms of an arbitrary function.

4. Explicit analytical expression of Riemann Xi function $\xi(s)$.

To derive the exact analytical expression of $\xi(s)$ we state a result of analysis in the form of a theorem.

The theorem is due to J. Brill [8]

Theorem 1. (Due to J. Brill)

The theorem states that if α is a root of

$$A\alpha^2 + B\alpha + C = 0 \quad A, B, C \text{ are constants} \quad \dots(4.1)$$

Then $\varphi(y + \alpha x)$ can be expressed as

$$\varphi(y + \alpha x) = \eta + \alpha\theta \quad \dots(4.2)$$

where α is independent of x, y and $\eta = \eta(x, y)$, $\theta = \theta(x, y)$ satisfy

$$\frac{1}{A} \frac{\partial \theta}{\partial y} = \frac{1}{B} \left(\frac{\partial \eta}{\partial y} - \frac{\partial \theta}{\partial x} \right) = -\frac{1}{C} \frac{\partial \eta}{\partial x} \quad \dots(4.3)$$

We will use the results from (4.1) to (4.3) of above theorem to find analytic expression of Riemann Xi function $\xi(s)$, where s is complex. Conventionally s is written as

$$s = \sigma + it ; \quad i = \sqrt{-1} \quad \dots(4.4)$$

σ, t being real and imaginary parts of s respectively.

Now from (4.3) we find

$$\frac{1}{A} \frac{\partial \theta}{\partial y} + \frac{1}{C} \frac{\partial \eta}{\partial x} = 0 \quad \dots(4.5)$$

$$\frac{1}{A} \frac{\partial \theta}{\partial y} - \frac{1}{B} \frac{\partial \eta}{\partial y} + \frac{1}{B} \frac{\partial \theta}{\partial x} = 0 \quad \dots(4.6)$$

$$\frac{1}{C} \frac{\partial \eta}{\partial x} + \frac{1}{B} \frac{\partial \eta}{\partial y} - \frac{1}{B} \frac{\partial \theta}{\partial x} = 0 \quad \dots(4.7)$$

From (4.7) one finds

$$\frac{1}{C} \frac{\partial^2 \eta}{\partial y \partial x} + \frac{1}{B} \frac{\partial^2 \eta}{\partial y^2} - \frac{1}{B} \frac{\partial^2 \theta}{\partial y \partial x} = 0 \quad \dots(4.8)$$

and from (4.5)
$$\frac{1}{A} \frac{\partial^2 \theta}{\partial x \partial y} + \frac{1}{C} \frac{\partial^2 \eta}{\partial x^2} = 0 \quad \dots(4.9)$$

Now from (4.8) and (4.9) eliminating $\frac{\partial^2 \theta}{\partial x \partial y}$ we get assuming partial derivatives are continuous

$$\frac{\partial^2 \eta}{\partial x^2} + \frac{B}{A} \frac{\partial^2 \eta}{\partial x \partial y} + \frac{C}{A} \frac{\partial^2 \eta}{\partial y^2} = 0 \quad \dots(4.10)$$

Likewise from (4.5)

$$\frac{\partial^2 \theta}{\partial y^2} + \frac{A}{C} \frac{\partial^2 \eta}{\partial x \partial y} = 0 \quad \dots(4.11)$$

And from (4.6)

$$\frac{1}{A} \frac{\partial^2 \theta}{\partial x \partial y} - \frac{1}{B} \frac{\partial^2 \eta}{\partial x \partial y} + \frac{1}{B} \frac{\partial^2 \theta}{\partial x^2} = 0 \quad \dots(4.12)$$

Again assuming partial derivatives are continuous, we eliminate $\frac{\partial^2 \eta}{\partial x \partial y}$ from (4.11) and (4.12).

The result is :

$$\frac{\partial^2 \theta}{\partial x^2} + \frac{B}{A} \frac{\partial^2 \theta}{\partial x \partial y} + \frac{C}{A} \frac{\partial^2 \theta}{\partial y^2} = 0 \quad \dots(4.13)$$

A comparison of (4.10) and (4.13) shows that we can choose

$$\eta(x, y) = \theta(x, y) \quad \dots(4.14)$$

Now in (4.1) we take

$$\alpha = 1 \quad \dots (4.15)$$

And in (4.2) we take

$$\left. \begin{array}{l} y = (\sigma - \frac{1}{2}) \\ x = i t \end{array} \right] \quad \dots (4.16)$$

Then in view of (4.15) we find from (4.1)

$$A + B + C = 0 \quad \dots (4.17)$$

and from (4.2), (4.14), (4.15) and (4.16)

$$\varphi(\sigma - \frac{1}{2} + i t) = \eta(\sigma - \frac{1}{2}, i t) + \theta(\sigma - \frac{1}{2}, i t) \quad \dots (4.18)$$

Using (4.16), (4.10) can be rewritten as

$$-\frac{\partial^2 \eta}{\partial t^2} - \frac{iB}{A} \frac{\partial^2 \eta}{\partial t \partial (\sigma - \frac{1}{2})} + \frac{C}{A} \frac{\partial^2 \eta}{\partial (\sigma - \frac{1}{2})^2} = 0$$

$$\text{i.e., } \frac{\partial^2 \eta}{\partial t^2} + \frac{iB}{A} \frac{\partial^2 \eta}{\partial t \cdot \partial(\sigma - \frac{1}{2})} - \frac{C}{A} \frac{\partial^2 \eta}{\partial(\sigma - \frac{1}{2})^2} = 0$$

$$\text{i.e., } \frac{\partial^2 \eta}{\partial t^2} + \frac{iB}{A} \frac{\partial^2 \eta}{\partial t \cdot \partial(\sigma - \frac{1}{2})} + \frac{A+B}{A} \frac{\partial^2 \eta}{\partial(\sigma - \frac{1}{2})^2} = 0, \text{ using (4.17)}$$

$$\text{Therefore, } \frac{\partial^2 \eta}{\partial t^2} + ik \frac{\partial^2 \eta}{\partial t \cdot \partial(\sigma - \frac{1}{2})} + (1+k) \frac{\partial^2 \eta}{\partial(\sigma - \frac{1}{2})^2} = 0; \quad k = \frac{B}{A} = \text{constant} \quad \dots(4.19)$$

Likewise (4.13) reduces to

$$\frac{\partial^2 \theta}{\partial t^2} + ik \frac{\partial^2 \theta}{\partial t \cdot \partial(\sigma - \frac{1}{2})} + (1+k) \frac{\partial^2 \theta}{\partial(\sigma - \frac{1}{2})^2} = 0 \quad \dots(4.20)$$

Equation (4.2), (4.14), (4.18), (4.19) and (4.20) imply that (3.6) can be written as

$$\begin{aligned} \xi(s) &= \psi(s - \frac{1}{2}) \\ &= \psi(\sigma - \frac{1}{2} + i t) \\ &= \eta_0(\sigma - \frac{1}{2}, i t) + \theta_0(\sigma - \frac{1}{2}, i t) \end{aligned} \quad \dots(4.21)$$

Where η_0 and θ_0 satisfy (4.19) and (4.20) and

$$\eta_0 = \theta_0 \quad \dots(4.22)$$

Hence from (4.21) and (4.22) the expression for $\xi(s)$ can be written as

$$\xi(s) = 2\eta_0(\sigma - \frac{1}{2}, i t) \quad \dots(4.23)$$

where η_0 satisfies

$$\frac{\partial^2 \eta_0}{\partial t^2} + ik \frac{\partial^2 \eta_0}{\partial t \cdot \partial(\sigma - \frac{1}{2})} + (1+k) \frac{\partial^2 \eta_0}{\partial(\sigma - \frac{1}{2})^2} = 0 \quad \dots(4.24)$$

There exist methods for solution of (4.24). However we will use the method due to Forsyth [9].

We use a trial solution for (4.24) :

$$\eta_0 = A_0 e^{il_1 t + il_2(\sigma - \frac{1}{2})} \quad \dots (4.25)$$

$A_0 = \text{constant (real)}; \text{ and } l_1 \text{ real and positive}$

Then from (4.24), using (4.25) one finds

$$l_1^2 + ik l_1 l_2 + (1+k)l_2^2 = 0 \quad \dots(4.26)$$

Treating (4.26) as a quadratic in l_1

We get

$$l_1 = i l_2$$

$$\text{i.e., } l_2 = -i l_1 \quad \dots(4.27)$$

and

$$l_1 = -i(k+1)l_2$$

$$i, e., l_2 = \frac{il_1}{(k+1)} \quad \dots (4.28)$$

Thus we have two solutions of (4.25)

$$\eta_{0,1} = A_0 e^{il_1 t + l_1 \left(\sigma - \frac{1}{2}\right)} \quad [\text{Using (4.27)}] \quad \dots (4.29)$$

$$= A_0 e^{l_1 \left(\sigma - \frac{1}{2}\right)} [\text{Cos } l_1 t + i \text{Sin } l_1 t] \quad \dots (4.29A)$$

$$\eta_{0,2} = A_0 e^{il_1 t - \frac{l_1}{k+1} \left(\sigma - \frac{1}{2}\right)} \quad [\text{Using (4.28)}] \quad \dots (4.30)$$

$$= A_0 e^{-\frac{l_1}{k+1} \left(\sigma - \frac{1}{2}\right)} [\text{Cos } l_1 t + i \text{Sin } l_1 t] \quad \dots (4.30A)$$

Now it is known that $\xi(s)$ is an entire function i.e., analytic in the whole complex plane.

Here $\eta_{0,1}$ is an analytic function because $\eta_{0,1}$ satisfies Cauchy-Riemann equations.

But $\eta_{0,2}$ is not analytic for arbitrary values of k . For $k = -2$, $\eta_{0,2}$ is only analytic.

So we choose $k = -2$ in (4.30) and (4.30A).

But though the choice $k = -2$ makes $\eta_{0,2}$ analytic, $\eta_{0,2}$ becomes identical with $\eta_{0,1}$ for $k = -2$

So we choose $k = -2$, but the ansatz for η_0 in (4.25) leads to one solution of (4.24) which is given by (4.29) or (4.29A).

$$\text{Now we take another ansatz for } \eta_0 = A_0 e^{-il_1 t - il_2 \left(\sigma - \frac{1}{2}\right)} \quad \dots (4.31)$$

This ansatz when plugged into (4.24) gives once again

$$l_1^2 + ikl_1 l_2 + (1+k)l_2^2 = 0 \quad \dots (4.32)$$

Here also we get like previous case

$$l_2 = -i l_1 \quad \dots (4.33)$$

$$\text{and } l_2 = \frac{il_1}{(k+1)} \quad \dots (4.34)$$

with these values we find from (4.31)

$$\eta_{0,3} = A_0 e^{-il_1 t - l_1 \left(\sigma - \frac{1}{2}\right)} \quad \dots (4.35)$$

$$= A_0 e^{-l_1 \left(\sigma - \frac{1}{2}\right)} [\text{Cos } l_1 t - i \text{Sin } l_1 t] \quad \dots (4.35A)$$

$$\text{and } \eta_{0,4} = A_0 e^{-il_1 t + \frac{l_1}{k+1} \left(\sigma - \frac{1}{2}\right)}$$

$$= A_0 e^{\frac{l_1}{k+1} \left(\sigma - \frac{1}{2}\right)} [\text{Cos } l_1 t - i \text{Sin } l_1 t] \quad \dots (4.36)$$

$\eta_{0,3}$ turns out to be analytic whereas $\eta_{0,4}$ is analytic only for $k = -2$ and for $k = -2$, $\eta_{0,4}$ becomes identical with $\eta_{0,3}$.

So the ansatz (4.31) leads to one more solution like previous analysis. And this solution is $\eta_{0,3}$ given by (4.35) and (4.35A).

It can be checked that $\eta_{0,1}$ and $\eta_{0,3}$ are linearly independent solutions of (4.24) as Wronskian of $\eta_{0,1}$ and $\eta_{0,3}$ is nonzero.

The Wronskian of $\eta_{0,1}$ and $\eta_{0,3}$ is [from (4.29) and (4.35)]

$$\begin{aligned}
 W &= \begin{vmatrix} A_0 e^{il_1 t + l_1(\sigma - \frac{1}{2})} & A_0 e^{-il_1 t - l_1(\sigma - \frac{1}{2})} \\ \left\{ \frac{\partial}{\partial t} + \frac{\partial}{\partial(\sigma - \frac{1}{2})} \right\} A_0 e^{il_1 t + l_1(\sigma - \frac{1}{2})} & \left\{ \frac{\partial}{\partial t} + \frac{\partial}{\partial(\sigma - \frac{1}{2})} \right\} A_0 e^{-il_1 t - l_1(\sigma - \frac{1}{2})} \end{vmatrix} \\
 &= \begin{vmatrix} A_0 e^{il_1 t + l_1(\sigma - \frac{1}{2})} & A_0 e^{-il_1 t - l_1(\sigma - \frac{1}{2})} \\ (il_1 + l_1)A_0 e^{il_1 t + l_1(\sigma - \frac{1}{2})} & - (il_1 + l_1) A_0 e^{-il_1 t - l_1(\sigma - \frac{1}{2})} \end{vmatrix} \\
 &= - A_0^2 (l_1 + i l_1) - A_0^2 (l_1 + i l_1) \\
 &= - 2 A_0^2 (l_1 + i l_1) \neq 0
 \end{aligned}$$

The sum of two independent solutions is also a solution of (4.24) [9].

Hence we write the solution of (4.24) as [from (4.29A) and (4.35A)]

$$\begin{aligned}
 \eta_0 &= \eta_{0,1} + \eta_{0,3} \\
 &= A_0 e^{l_1(\sigma - \frac{1}{2})} [\cos l_1 t + i \sin l_1 t] + A_0 e^{-l_1(\sigma - \frac{1}{2})} [\cos l_1 t - i \sin l_1 t] \\
 &= 2A_0 \cos l_1 t \left\{ \frac{e^{l_1(\sigma - \frac{1}{2})} + e^{-l_1(\sigma - \frac{1}{2})}}{2} \right\} + i2A_0 \sin l_1 t \left\{ \frac{e^{l_1(\sigma - \frac{1}{2})} - e^{-l_1(\sigma - \frac{1}{2})}}{2} \right\} \\
 &= A_1 \cos l_1 t \cos h l_1(\sigma - \frac{1}{2}) + i A_1 \sin l_1 t \sin hl_1(\sigma - \frac{1}{2}); \quad 2 A_0 = A_1 \\
 &= A_1 [\cos l_1 t \cos h l_1(\sigma - \frac{1}{2}) + i \sin l_1 t \sin hl_1(\sigma - \frac{1}{2})] \quad \dots(4.37)
 \end{aligned}$$

The constant A_1 can be looked upon [9] as a function of the parameter l_1

So we write from (4.37)

$$\eta_0 = A_1(l_1) [\cos l_1 t \cos h l_1(\sigma - \frac{1}{2}) + i \sin l_1 t \sin hl_1(\sigma - \frac{1}{2})] \quad \dots(4.38)$$

Now, the solution of (4.24) should contain [9] two constants of the form $A_1(l_1)$; so the final expression of η_0 is of the form

$$\eta_0 = A_2(l_1) + A_1(l_1) [\text{Cos } l_1 t \text{ Cos } h l_1 (\sigma - \frac{1}{2}) + i \text{Sin } l_1 t \text{ Sin } h l_1 (\sigma - \frac{1}{2})] \quad \dots(4.39)$$

Using (4.23) and (4.39) we can now write the analytic expression of Riemann X_i function $\xi(s)$ as $\xi(s) = \xi(\sigma + it)$.

$$= 2\eta_0$$

$$= 2 A_2(l_1) + 2 A_1(l_1) [\text{Cos } l_1 t \text{ Cos } h l_1 (\sigma - \frac{1}{2}) + i \text{Sin } l_1 t \text{ Sin } h l_1 (\sigma - \frac{1}{2})]$$

$$\text{i.e., } \xi(s) = F_2(l_1) + F_1(l_1) [\text{Cos } l_1 t \text{ Cos } h l_1 (\sigma - \frac{1}{2}) + i \text{Sin } l_1 t \text{ Sin } h l_1 (\sigma - \frac{1}{2})] \quad \dots(4.40)$$

$$\text{where } F_2(l_1) = 2 A_2(l_1) \quad \text{and} \quad F_1(l_1) = 2 A_1(l_1)$$

$F_2(l_1)$ and $F_1(l_1)$ both being real

Equation (4.40) is the final analytic expression for Riemann X_i function $\xi(s)$. This solution is analytic and satisfies the equation (2.5) i.e., $\xi(s) = \xi(1 - s)$. The two constants $F_2(l_1)$ and $F_1(l_1)$ in (4.40) are functions of the parameter l_1 .

The solution (4.40) has certain advantage. It contains no arbitrary functions of the independent variables ; instead it contains two constants ; the constants being arbitrary functions of the parameter l_1 .

Now for $t = 0$, we have from (4.40)

$$\xi(\sigma) = F_2(l_1) + F_1(l_1) \text{Cos } h l_1 (\sigma - \frac{1}{2}) \quad \dots(4.41)$$

Now it is known that

$$\left. \begin{aligned} \xi(0) &= \xi(1) = \frac{1}{2} \\ \xi(2) &= \frac{\pi}{6} \approx 0.52 \\ \xi(3) &\approx 0.57 \\ \xi(4) &= \frac{\pi^2}{15} \approx 0.65 \end{aligned} \right\} \quad \dots(4.42)$$

Using (4.42) we find from (4.41)

$$F_2(l_1) + F_1(l_1) \text{Cosh } \frac{l_1}{2} = 0.50 \quad \dots(4.43)$$

$$F_2(l_1) + F_1(l_1) \text{Cosh } \frac{3l_1}{2} = 0.52 \quad \dots(4.44)$$

$$F_2(l_1) + F_1(l_1) \text{Cosh } \frac{5l_1}{2} = 0.57 \quad \dots(4.45)$$

$$F_2(l_1) + F_1(l_1) \text{Cosh } \frac{7l_1}{2} = 0.65 \quad \dots(4.46)$$

As zeros of $\xi(s)$ are only complex, $\xi(\sigma)$ has no real zeros. And cosine hyperbolic function being always positive, $F_2(l_1)$ and $F_1(l_1)$ are assumed to be positive as suggested by equations (4.43) to (4.46).

Now it is an easy task [Appendix] to check that the parameter l_1 and the arbitrary function $F_1(l_1)$, $F_2(l_1)$ cannot be determined uniquely from the equations (4.43) to (4.46) or other equations formed from equation (4.41) with known values of $\xi(\sigma)$.

Thus l_1 , $F_1(l_1)$, $F_2(l_1)$ in (4.40), (4.41) and in (4.43) to (4.46) are undetermined. However the non-existence of unique solution of the system (4.43) to (4.46) cannot prevent proving Riemann Hypothesis.

5. Proof of Riemann Hypothesis and analytical expression for zeros of $\xi(s)$ (i.e., nontrivial zeros of $\zeta(s)$)

The proof of Riemann Hypothesis is concerned with the form of nontrivial zeros of Riemann Zeta function $\zeta(s)$ i.e., the zeros of Riemann Xi function $\xi(s)$.

The zeros of $\xi(s)$ imply that both real and imaginary parts of equation (4.40) are zero. Therefore zero of $\xi(s)$ imply

$$\text{Real } \xi(s) = R_E = F_2(l_1) + F_1(l_1) \text{Cos } l_1 t \text{Cos } h l_1 \left(\sigma - \frac{1}{2} \right) = 0 \quad \dots(5.1)$$

$$\text{and Imaginary } \xi(s) = I_M = F_1(l_1) \text{Sin } l_1 t \text{Sin } h l_1 \left(\sigma - \frac{1}{2} \right) = 0 \quad \dots (5.2)$$

Firstly we ignore considering $R_E = 0$. Because $R_E = 0$ implies $F_2(l_1) = 0$ along with either $F_1(l_1)$ or $\text{Cos } l_1 t$ equal to zero as $\text{Cos } h l_1 \left(\sigma - \frac{1}{2} \right)$ is always defined to be positive. But $F_2(l_1)$ and $F_1(l_1)$ are both non zero. Hence this conclusion.

Now as $F_2(l_1) \neq 0$ and $F_1(l_1) \neq 0$, as a second possibility, $I_M = 0$ requires to find a value of σ ($0 < \sigma < 1$) for which $\text{Sin } h l_1 \left(\sigma - \frac{1}{2} \right) = 0$. And for $\text{Sin } h l_1 \left(\sigma - \frac{1}{2} \right) = 0$, we can find the condition for $R_E = 0$ from equation (5.1).

As a third possibility when $\text{Sin } h l_1 \left(\sigma - \frac{1}{2} \right) \neq 0$, $I_M = 0$ implies $\text{Sin } l_1 t = 0$ and $R_E = 0$ would imply $\text{Cos } h l_1 \left(\sigma - \frac{1}{2} \right) = \pm \frac{F_2(l_1)}{F_1(l_1)}$, as $\text{Cos } l_1 t = \pm 1$ when $\text{Sin } l_1 t = 0$. This possibility is ruled out because $\pm \frac{F_2(l_1)}{F_1(l_1)}$ is independent of σ .

Now considering the second possibility a look into equation (5.1) and (5.2) assert that only for $\sigma = \frac{1}{2}$, $\text{Sinh } l_1 \left(\sigma - \frac{1}{2} \right) = 0$ and so $I_M = 0$. And condition for $R_E = 0$ follows from (5.1) with $\sigma = \frac{1}{2}$:

$$\text{Cos } l_1 t = - \frac{F_2(l_1)}{F_1(l_1)} \quad \dots(5.3)$$

Therefore the nontrivial zeros of $\zeta(s)$ turn out to be of the form $\left(\frac{1}{2} + it \right)$ where t is given by (5.3) or more explicitly

$$t = \frac{1}{l_1} \text{Cos}^{-1} \left[- \frac{F_2(l_1)}{F_1(l_1)} \right] \quad \dots(5.4)$$

As l_1 , $F_2(l_1)$, $F_1(l_1)$ are unknown, we cannot compute the value of t from (5.4).

Thus the proof of Riemann Hypothesis is established.

6. A second proof of Riemann Hypothesis :

The second of proof of Riemann Hypothesis is proof of a result which is equivalent to proof of Riemann Hypothesis. This Riemann Hypothesis equivalent is due to Brian Conrey [10]. Conrey has shown that the truth of Riemann Hypothesis is equivalent to proving that zeros of derivatives of all orders of Riemann Xi functions $\xi(s)$ has real part $\sigma = \frac{1}{2}$. We will prove this in the following .

From equation (4.40) we write once again the expression for Riemann Xi functions $\xi(s)$:

$$\begin{aligned} \xi(s) &= \xi(\sigma + it) \\ &= [F_2(l_1) + F_1(l_1) \text{Cos } l_1 t \text{Cos h } l_1 \left(\sigma - \frac{1}{2} \right)] + i [F_1(l_1) \text{Sin } l_1 t \text{Sin hl}_1 \left(\sigma - \frac{1}{2} \right)] \quad \dots(6.1) \end{aligned}$$

$$\begin{aligned} \text{Therefore } \frac{d}{ds} \xi(s) &= \xi^{(1)}(s) \\ &= \frac{\partial}{\partial \sigma} [F_2(l_1) + F_1(l_1) \text{Cos } l_1 t \text{Cos h } l_1 \left(\sigma - \frac{1}{2} \right)] + i \frac{\partial}{\partial \sigma} [F_1(l_1) \text{Sin } l_1 t \text{Sin hl}_1 \left(\sigma - \frac{1}{2} \right)] \\ &= l_1 F_1(l_1) \text{Cos } l_1 t \text{Sin h } l_1 \left(\sigma - \frac{1}{2} \right) + i l_1 F_1(l_1) \text{Sin } l_1 t \text{Cos h } l_1 \left(\sigma - \frac{1}{2} \right) \quad \dots(6.2) \end{aligned}$$

$$\begin{aligned} \text{Likewise } \frac{d^2}{ds^2} \xi(s) &= \xi^{(2)}(s) \\ &= l_1^2 F_1(l_1) \text{Cos } l_1 t \text{Cos h } l_1 \left(\sigma - \frac{1}{2} \right) + i l_1^2 F_1(l_1) \text{Sin } l_1 t \text{Sin hl}_1 \left(\sigma - \frac{1}{2} \right) \quad \dots(6.3) \end{aligned}$$

$$\begin{aligned}
& \frac{d^{2m}}{ds^{2m}} \xi(s) \\
& = \xi^{(2m)}(s) \\
& = l_1^{2m} F_1(l_1) \cos l_1 t \cos h l_1 \left(\sigma - \frac{1}{2} \right) + i l_1^{2m} F_1(l_1) \sin l_1 t \sin h l_1 \left(\sigma - \frac{1}{2} \right) \quad \dots(6.4)
\end{aligned}$$

$$\begin{aligned}
\text{And } & \frac{d^{2m+1}}{ds^{2m+1}} \xi(s) \\
& = \xi^{(2m+1)}(s) \\
& = l_1^{2m+1} F_1(l_1) \cos l_1 t \sin h l_1 \left(\sigma - \frac{1}{2} \right) + i l_1^{2m+1} F_1(l_1) \sin l_1 t \cos h l_1 \left(\sigma - \frac{1}{2} \right) \quad \dots(6.5)
\end{aligned}$$

Now we first consider the zeros of $\frac{d^{2m}}{ds^{2m}} \xi(s)$.

From (6.4) zeros of $\frac{d^{2m}}{ds^{2m}} \xi(s)$ imply

$$l_1^{2m} F_1(l_1) \cos l_1 t \cos h l_1 \left(\sigma - \frac{1}{2} \right) = 0 \quad \dots(6.6)$$

$$\text{And } l_1^{2m} F_1(l_1) \sin l_1 t \sin h l_1 \left(\sigma - \frac{1}{2} \right) = 0 \quad \dots(6.7)$$

Now suppose $\sigma \neq \frac{1}{2}$ then $\cos h l_1 \left(\sigma - \frac{1}{2} \right) \neq 0$ and $\sin h l_1 \left(\sigma - \frac{1}{2} \right) \neq 0$ then (6.6) and (6.7) imply both $\cos l_1 t = 0$ as well as $\sin l_1 t = 0$ which is impossible.

On the other hand if $\sigma = \frac{1}{2}$ equation (6.7) is satisfied because $\sin h 0 = 0$ and (6.6) implies $\cos l_1 t = 0$ (as $\cos h 0 \neq 0$)

$$\text{i.e., } l_1 t = (2n + 1) \frac{\pi}{2}$$

$$\text{i.e., } t = \frac{1}{l_1} (2n + 1) \frac{\pi}{2} \quad \dots(6.8)$$

Thus it turns out that zeros of $\xi^{(2m)}(s)$ are of the form $\frac{1}{2} + i \frac{1}{l_1} (2n + 1) \frac{\pi}{2}$ where l_1 is an undetermined parameter.

We next consider the zeros of $\xi^{(2m+1)}(s)$

From (6.5) zeros of $\xi^{(2m+1)}(s)$ imply

$$l_1^{2m+1} F_1(l_1) \cos l_1 t \sin h l_1 \left(\sigma - \frac{1}{2} \right) = 0 \quad \dots(6.9)$$

$$l_1^{2m+1} F_1(l_1) \sin l_1 t \cos h l_1 \left(\sigma - \frac{1}{2} \right) = 0 \quad \dots(6.10)$$

A similar argument as above reveals that zeros of $\xi^{(2m+1)}(s)$ has real part $\sigma = \frac{1}{2}$ and imaginary part is given by

$$\sin l_1 t = 0$$

$$\text{i.e., } l_1 t = n\pi$$

$$\text{i.e., } t = \frac{1}{l_1} n\pi$$

Therefore zeros of $\xi^{(2m+1)}(s)$ are of the form $\frac{1}{2} + i \frac{1}{l_1} n\pi$

Thus the second proof of Riemann Hypothesis is established.

It is interesting to observe from above analysis that zeros of all even order derivatives of $\xi(s)$ are identical and zeros of all odd order derivatives of $\xi(s)$ are also identical.

7. Third Proof of Riemann Hypothesis

We will now prove another Riemann Hypothesis equivalent due to J. C. Lagarias [11]. This Riemann Hypothesis equivalent asserts that Riemann Hypothesis implies

$$\text{Real} \left(\frac{\xi'(s)}{\xi(s)} \right) > 0 \text{ for Real } S > \frac{1}{2} \quad (7.1)$$

The proof of this equivalent proceeds as follows

It was shown before that analytic expression of Riemann Xi function $\xi(s)$ has the following form.

$$\begin{aligned} \xi(s) &= \xi(\sigma + it) \\ &= F_2(l_1) + F_1(l_1) [\text{Cos } l_1 t \text{ Cos } h l_1 \left(\sigma - \frac{1}{2} \right) + i \text{Sin } l_1 t \text{ Sin } h l_1 \left(\sigma - \frac{1}{2} \right)] \end{aligned} \quad (7.2)$$

Using the identity $\text{Cos } x = \text{Cosh } ix$ and $i \text{Sin } x = \text{Sinh } ix$ (7.2) can be written as

$$\begin{aligned} \xi(s) &= \xi(\sigma + it) \\ &= F_2(l_1) + F_1(l_1) [\text{Coshi } l_1 t \text{ Cos } h l_1 \left(\sigma - \frac{1}{2} \right) + \text{Sinhi } l_1 t \text{ Sin } h l_1 \left(\sigma - \frac{1}{2} \right)] \\ &= F_2(l_1) + F_1(l_1) \text{Cosh} [il_1 t + l_1 \left(\sigma - \frac{1}{2} \right)] \end{aligned} \quad (7.3)$$

$$\begin{aligned} \text{Therefore } \xi'(s) &= \frac{d}{ds} \xi(s) \\ &= \frac{\partial}{\partial \sigma} \xi(s) = l_1 F_1(l_1) \text{Sinh} [il_1 t + l_1 \left(\sigma - \frac{1}{2} \right)] \end{aligned} \quad (7.4)$$

Hence from (7.4) and (7.3)

$$\frac{\xi'(s)}{\xi(s)} = \frac{l_1 F_1(l_1) \text{Sinh} [il_1 t + l_1 \left(\sigma - \frac{1}{2} \right)]}{F_2(l_1) + F_1(l_1) \text{Cosh} [il_1 t + l_1 \left(\sigma - \frac{1}{2} \right)]} \quad (7.5)$$

Therefore

$$\text{Real} \left(\frac{\xi'(s)}{\xi(s)} \right) = \frac{l_1 F_1(l_1) \text{Sinh} [l_1 \left(\sigma - \frac{1}{2} \right)]}{F_2(l_1) + F_1(l_1) \text{Cosh} [l_1 \left(\sigma - \frac{1}{2} \right)]} \quad (7.6)$$

For $\sigma > \frac{1}{2}$, R.H.S of (7.6) is always positive. Because $\text{Sinh} [l_1 \left(\sigma - \frac{1}{2} \right)] > 0$ for $\sigma > \frac{1}{2}$ and $\text{Cosh} [l_1 \left(\sigma - \frac{1}{2} \right)]$ is always positive and $l_1, F_2(l_1), F_1(l_1)$ are positive as mentioned earlier.

Thus it turns out that

$$\text{Real} \left(\frac{\xi'(s)}{\xi(s)} \right) > 0 \text{ for } \sigma > \frac{1}{2}$$

This completes the proof of Riemann Hypothesis.

8. Conclusion:

In this paper three proofs of Riemann Hypothesis are given. The first proof may be called a direct proof. It is not a proof of any Riemann Hypothesis equivalent [12, 13]. It fails to identify the position of nontrivial zeros of $\zeta(s)$ on critical axis. However it confirms that all the nontrivial zeros of $\zeta(s)$ lie on critical axis. The second and third proofs are proof of Riemann Hypothesis equivalents. We can now safely conclude that Riemann Hypothesis is not at all trifling or baffling. It is perfectly true.

Appendix

We write equations (4.43) to (4.46) once again

$$F_2(l_1) + F_1(l_1) \operatorname{Cosh} \frac{l_1}{2} = 0.50 \quad \dots(\text{A1})$$

$$F_2(l_1) + F_1(l_1) \operatorname{Cosh} \frac{3l_1}{2} = 0.52 \quad \dots(\text{A2})$$

$$F_2(l_1) + F_1(l_1) \operatorname{Cosh} \frac{5l_1}{2} = 0.57 \quad \dots(\text{A3})$$

$$F_2(l_1) + F_1(l_1) \operatorname{Cosh} \frac{7l_1}{2} = 0.65 \quad \dots(\text{A4})$$

Now (A2) – (A1) gives

$$F_1(l_1) \left[\operatorname{Cosh} \frac{3l_1}{2} - \operatorname{Cosh} \frac{l_1}{2} \right] = 0.02$$

Therefore $F_1(l_1) \cdot 2 \cdot \operatorname{Sinh} l_1 \cdot \operatorname{Sinh} \frac{l_1}{2} = 0.02 \quad \dots(\text{A5})$

(A3) – (A2) gives

$$F_1(l_1) \left[\operatorname{Cosh} \frac{5l_1}{2} - \operatorname{Cosh} \frac{3l_1}{2} \right] = 0.05$$

Therefore $F_1(l_1) \cdot 2 \cdot \operatorname{Sinh} 2l_1 \cdot \operatorname{Sinh} \frac{l_1}{2} = 0.05 \quad \dots(\text{A6})$

(A4) – (A3) gives

$$F_1(l_1) \left[\operatorname{Cosh} \frac{7l_1}{2} - \operatorname{Cosh} \frac{5l_1}{2} \right] = 0.08$$

Therefore $F_1(l_1) \cdot 2 \cdot \operatorname{Sinh} 3l_1 \cdot \operatorname{Sinh} \frac{l_1}{2} = 0.08 \quad \dots(\text{A7})$

(A4) – (A2) gives

$$F_1(l_1) \left[\operatorname{Cosh} \frac{7l_1}{2} - \operatorname{Cosh} \frac{3l_1}{2} \right] = 0.13$$

Therefore $F_1(l_1) \cdot 2 \cdot \operatorname{Sinh} 5l_1 \cdot \operatorname{Sinh} l_1 = 0.13 \quad \dots(\text{A8})$

Next (A6) ÷ (A5) gives

$$\frac{\operatorname{Sinh} 2l_1}{\operatorname{Sinh} l_1} = \frac{0.05}{0.02} = \frac{5}{2}$$

Therefore $\operatorname{Cosh} l_1 = \frac{5}{4} = 1.25 \quad \dots(\text{A9})$

Again (A7) \div (A6) gives

$$\frac{\text{Sinh}3l_1}{\text{Sinhl}_1} = \frac{0.08}{0.05} = \frac{8}{5}$$

i.e.,
$$\frac{4\text{Sinh}^3l_1 + 3\text{Sinhl}_1}{2\text{Sinhl}_1 \cdot \text{Coshl}_1} = \frac{8}{5}$$

i.e.,
$$\frac{4\text{Sinh}^2l_1 + 3}{\text{Coshl}_1} = \frac{16}{5}$$

i.e.,
$$4(\text{Cosh}^2 l_1 - 1) + 3 = \frac{16}{5} \text{Cosh } l_1$$

i.e.,
$$4\text{Cosh}^2 l_1 - \frac{16}{5} \text{Cosh } l_1 - 1 = 0$$

Therefore
$$\begin{aligned} \text{Cosh } l_1 &= \frac{\frac{16}{5} \pm \sqrt{\left(\frac{16}{5}\right)^2 + 16}}{8} \\ &= \frac{3.2 \pm \sqrt{(3.2)^2 + 16}}{8} \\ &= \frac{3.2 \pm \sqrt{26.24}}{8} \end{aligned}$$

As $\text{Cosh } l_1$ is defined always to be positive, hence we get from above

$$\text{Cosh } l_1 = \frac{3.2 + \sqrt{26.24}}{8} = \frac{3.2 + 5.12}{8} = \frac{8.32}{8} = 1.04 \quad \dots(\text{A10})$$

A comparison of (A9) and (A10) shows that l_1 cannot be uniquely determined and consequently $F_1(l_1)$ and $F_2(l_1)$ remain undetermined uniquely.

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