

The Center and the Barycenter

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March 3, 2021

In the first part we deal with the question which points we have to connect to generate a non self-intersecting polygon. Afterwards we introduce *polyholes*, which is a generalization of polygons. Roughly spoken a polyhole is a big polygon, where we cut out a finite number of small polygons.

In the second part we present two ‘centers’, which we call *center* and *barycenter*. In the case that both centers coincide, we call these polygons as *nice*. We show that if a polygon has two symmetry axes, it is nice. We yield examples of polygons with a single symmetry axis which are nice and which are not nice.

In a third part we introduce the *Spieker center* and the *Point center* for polygons. We define *beautiful* polygons and *perfect* polygons. We show that all symmetry axes intersect in a single point.

Keywords and phrases: barycenter, polygon

MSC 2020: 51-08

1 Introduction

We look for a criterion to generate a simple polygon.

Let us assume a set of $k + 1$ points called *Points* $\subset \mathbb{R}^2$, $Points := \{(x_1, y_1), (x_2, y_2), \dots, (x_{k-1}, y_{k-1}), (x_k, y_k), (x_{k+1}, y_{k+1})\}$. We joint the possible edges. We define the subset *Union* of \mathbb{R}^2 , $Union := \bigcup \{(x_i, y_i), (x_{i+1}, y_{i+1})\}$ for $i \in \{1, 2, \dots, k-1, k\}$. With the expression ‘ $[a, b]$ ’ we mean all points between a and b and the boundaries a and b . We say that *Union* is *suitable* if and only if *Union* is homeomorphic to the circle $\{x^2 + y^2 = 1 \mid x, y \in \mathbb{R}\}$.

Definition 1.1. We presume $k + 1$ points (x_i, y_i) of \mathbb{R}^2 where $1 \leq i \leq k + 1$ and $k > 2$. We name *Union* as a *polygon* if and only if it holds $(x_{k+1}, y_{k+1}) = (x_1, y_1)$. The element (x_i, y_i) is called a *vertex*. We call a polygon such that *Union* is suitable as *simple polygon*. If we have a simple polygon we include its interior.

2 Star-Shaped Polygons

We can start also with a circle $\{(x, y) \in \mathbb{R}^2 \mid x^2 + y^2 = 1\}$, We presume a finite set called A of k different points on the circle, where $k > 2$ and $A := \{\vec{a}_1, \vec{a}_2, \dots, \vec{a}_{k-1}, \vec{a}_k\}$ is in counterclockwise

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order. We change it into a set $H := \{\vec{h}_1, \vec{h}_2, \dots, \vec{h}_{k-1}, \vec{h}_k\}$ such that the three points \vec{h}_i, \vec{a}_i and $(0, 0)$ are collinear and $(0, 0)$ is not between \vec{a}_i and \vec{h}_i . We keep the order as in A . We move all points with the same vector \vec{m} , i.e. $Z := \{\vec{z}_1, \vec{z}_2 \dots \vec{z}_i \dots \vec{z}_{k-1}, \vec{z}_k\} \subset \mathbb{R}^2$ where $1 \leq i \leq k$ and $\vec{z}_i := \vec{h}_i + \vec{m}$. We keep the order. We call a polygon with a set of vertices $Z := \{\vec{z}_1, \vec{z}_2, \dots, \vec{z}_{k-1}, \vec{z}_k\}$ as a *star-shaped polygon* if and only if Z provided with an appropriate order can be constructed as it is just described. We add $\vec{z}_{k+1} := \vec{z}_1$. Please see the following Proposition 2.2.

Question 2.1. *Is there an alternative description of star-shaped polygons? Is every convex simple polygon a star-shaped polygon?*

Proposition 2.2. *We get a simple polygon P if there is a finite set of points $Z := \{\vec{z}_1, \vec{z}_2, \dots, \vec{z}_{k-1}, \vec{z}_k, \vec{z}_{k+1}\} \subset \mathbb{R}^2$ constructed as above where $k > 2$ and*

$P := \bigcap \{ W \subset \mathbb{R}^2 \mid Z \subset W, \text{ where } W \text{ is homeomorphic to the circle area } \{x^2 + y^2 \leq 1\} \text{ and the points between } \vec{z}_i \text{ and } \vec{z}_{i+1}, 1 \leq i \leq k-1, \text{ including } \vec{z}_i \text{ and } \vec{z}_{i+1} \text{ are a subset of } W \text{ and also the points between } \vec{z}_k \text{ and } \vec{z}_1 \text{ belong to } W \}$

Proof. The claim of the proposition is trivial, since *Union* is a suitable set. □

It follows that a star-shaped polygon is a compact set, homeomorphic to any circle, and for all $1 \leq i \leq k$ the vertex \vec{z}_i is a boundary point.

We get that a triangle is a star-shaped polygon, too.

We assume a set of points $\{(x_1, y_1), (x_2, y_2), (x_3, y_3), \dots, (x_{k-1}, y_{k-1}), (x_k, y_k), (x_{k+1}, y_{k+1})\}$ of \mathbb{R}^2 . We call this set *Points*. We demand that in *Points* three successive elements are distinct and not collinear. We assume $k > 2$. We connect the points of *Points* by the given order and we call this set *Union*. In the case that *Union* is homeomorphic to a circle we get a simple polygon. For $k = 3$ the polygon is a triangle.

Proposition 2.3. *If we have a set of $k + 1$ points $Points := \{(x_1, y_1), (x_2, y_2), \dots, (x_k, y_k), (x_{k+1}, y_{k+1})\}$ with $(x_{k+1}, y_{k+1}) = (x_1, y_1)$ and $k > 2$, we get a simple polygon if and only if the set *Union* is suitable.*

Proof. Trivial. □

3 Polyholes

We define a subset of \mathbb{R}^2 , which we will call a *polyhole*. This geometric structure consists of a finite number of simple polygons $P, P_1, P_2, P_3, \dots, P_{m-1}, P_m$. From the polygon P we cut out polygons $P_1, P_2, P_3, \dots, P_{m-1}, P_m$.

Definition 3.1. Let $\{P, P_1, P_2, P_3, \dots, P_{m-1}, P_m\}$ be a set of simple polygons. A *polyhole* is defined as P without $P_1 \cup P_2 \cup P_3 \cup \dots \cup P_{m-1} \cup P_m$

A corresponding definition is possible for polytopes.

Definition 3.2. Let $\{P, P_1, P_2, P_3, \dots, P_{m-1}, P_m\}$ be a set of polytopes in \mathbb{R}^n . A *polytophole* is defined as P without $P_1 \cup P_2 \cup P_3 \cup \dots \cup P_{m-1} \cup P_m$.

Question 3.3. *What is the barycenter of a polyhole, if it is realized with homogeneous material of constant thickness? What is the barycenter of a polytophole in \mathbb{R}^3 , if it is realized with homogeneous material?*

4 Nice Polygons

We define two ‘centers’, where the center $Cent$ is just the arithmetic means of the first and second coordinates of the generating points, respectively.

We got the following formulas for the *barycenter* $B = (B_x, B_y)$ of a simple polygon from [1] or [2]. Please see also [3] and [4]. $Area$ is the area of a simple polygon. Note that $Area \neq 0$, and that in [1] and [3] the barycenter is called a Centroid, and further that B is the center of gravity of the polygon, if it is realized with homogeneous material of constant thickness. Note that the order in the polygon is counterclockwise. We write

$$D_i = x_i \cdot y_{i+1} - x_{i+1} \cdot y_i, \text{ where } 1 \leq i \leq k \quad (4.1)$$

$$Area = \frac{1}{2} \cdot \sum_{i=1}^k D_i \quad (4.2)$$

$$B_x = \frac{1}{6 \cdot Area} \cdot \sum_{i=1}^k (x_i + x_{i+1}) \cdot D_i, \quad B_y = \frac{1}{6 \cdot Area} \cdot \sum_{i=1}^k (y_i + y_{i+1}) \cdot D_i \quad (4.3)$$

$$Cent = \frac{1}{k} \cdot \left(\sum_{i=1}^k x_i, \sum_{i=1}^k y_i \right) \quad (4.4)$$

Definition 4.1. Let us presume a simple polygon P . We call P *nice* if and only if it holds $B = Cent$.

Remark 4.2. When we use the term *symmetry axis of a polygon* P we mean a line segment s in the convex hull of P of maximal length, i.e. it holds for a symmetry axis t in the convex hull of P with more than one common point with s that $t \subset s$.

Proposition 4.3. *If a simple polygon has two different symmetry axes, it is nice*

Proof. The proposition is an easy consequence of the following important two lemmas.

Lemma 4.4. *Let P be a polygon. The following two operations yield a polygon again. The property of being nice or being not nice remain under these operations.*

- *Revolving P by an arbitrary angle around any point*
- *Shifting P by an arbitrary vector*

Proof. We assume $B \neq Cent$. Let us revolve P by an arbitrary angle around any point. There is a positive distance d between B and $Cent$. It will be kept, since a rotation is a distance preserving map. Hence the distance between the images points of B and $Cent$ is also d . After the rotation still P is not nice.

In the case $B = Cent$ the claim of the lemma is trivial. □

Lemma 4.5. *Both operations which we have mentioned above in Lemma 4.4 are distance preserving operations. Therefore the shape of a polygon is kept after these operations.*

Proof. Trivial. □

In a polygon we fix four real numbers.

Definition 4.6. Let $Points$ be the set of vertices of a polygon P . We define
 $min_x :=$ minimum of the set of the first coordinates of the set of the vertices $Points$ of P .
 $min_y :=$ minimum of the second coordinates of $Points$,
 $max_x :=$ maximum of the first coordinates of $Points$,
 $max_y :=$ maximum of the second coordinates of $Points$.

We define a rectangle called $Rectangle(P)$ by four vertices
 $(max_x, max_y), (min_x, max_y), (min_x, min_y), (max_x, min_y)$.

Remark 4.7. In a polygon P it holds that both P and the convex hull of $Points$ is in $Rectangle(P)$.

Definition 4.8. Let $s = \{\vec{a} + r \cdot \vec{d} \mid r \in [m, n]\}$ for fixed real numbers m, n be a symmetry axis of a polygon. We define $l(s)$ as the line $\{\vec{a} + r \cdot \vec{d} \mid r \in \mathbb{R}\}$.

Remark 4.9. It holds that s is a subset of $l(s)$.

Lemma 4.10. *Let s be a symmetry axis of a simple polygon P . Both B and $Cent$ are on the line $l(s) \cap Rectangle(P)$.*

Proof. We assume a simple polygon P with a symmetry axis s and centers B and $Cent$. Note that B is the center of gravity of P . Hence B must be on $l(s)$, since s is a symmetry axis of P . For the same reason B is in $Rectangle(P)$.

We use Lemma 4.5. We map P by a rotation and a shift parallel the vertical y axis into a second polygon P' with a symmetry axis s' and centers B' and $Cent'$ such that s' is on the x axis. Assume a vertex (x', y') of P' . Since s' is a symmetry axis and it is on the x axis either $y' = 0$ or there is a second vertex $(x', -y')$ of P' . If we add all vertices together we get $Cent' = (c', 0)$ with any real number c' , i.e. $Cent'$ is on the x axis. This means that $Cent'$ is on $l(s')$. Since P' has the same shape as P we get that $Cent$ is on $l(s)$.

It is easy to show that $Cent$ is a point in $Rectangle(P)$: It holds

$$min_x = \frac{1}{k} \cdot \sum_{i=1}^k min_x \leq \frac{1}{k} \sum_{i=1}^k x_i \leq \frac{1}{k} \sum_{i=1}^k max_x = max_x \quad (4.5)$$

If we consider correspondingly the second coordinate of $Cent$ we get $min_y \leq \frac{1}{k} \sum_{i=1}^k y_i \leq max_y$, and it follows that $Cent$ is in $Rectangle(P)$.

We get that $Cent$ is in $l(s) \cap Rectangle(P)$. Lemma 4.10 has been proved. □

Two symmetry axes intersect in a single point. It is both B and $Cent$. The proof of Proposition 4.3 is finished. \square

Corollary 4.11. In a simple polygon all symmetry axes intersect in a single point. It is both B and $Cent$. It follows that a simple polygon with more than one symmetry axis is nice.

Note that a single symmetry axis is not sufficient, as the kite defined by $(0, 0), (1, -1), (3, 0), (1, 1)$ shows, since $\frac{5}{4} \neq \frac{4}{3}$. It is not nice.

It follows an example of a polygon with a single symmetry axis which is nice.

Take the 5-gon with vertices

$$(0, 0), (1, 0), (1, 1), \left(\frac{1}{2}, 1 + \frac{1}{2} \cdot \sqrt{6}\right), (0, 1). \text{ We get } B = Cent = \left(\frac{1}{2}, \frac{1}{10} \cdot (6 + \sqrt{6})\right) \approx (0.50, 0.85) \quad (4.6)$$

The last example proves that the conjecture that besides triangles only polygons with two or more symmetry axes are nice is wrong.

5 Spieker Center and Point Center

In a triangle the Spieker center is well-known. We have got the formulas of the Spieker center from [4]. Please see also [5]. The Spieker center is the barycenter of a triangle $A = (x_A, y_A), B = (x_B, y_B), C = (x_C, y_C)$ without the interior, which is formed by a wire of constant thickness. The barycenter is outside the wire. The sidelengths of the triangle are l_1, l_2 and l_3 , where sides with lengths l_2 and l_3 intersect in A , while sides with lengths l_1 and l_3 intersect in B . The coordinates of the Spieker center $S = (spieker_x, spieker_y)$ are

$$spieker_x = \frac{(l_2 + l_3) \cdot x_A + (l_1 + l_3) \cdot x_B + (l_1 + l_2) \cdot x_C}{2 \cdot (l_1 + l_2 + l_3)} \quad \text{and} \quad (5.1)$$

$$spieker_y = \frac{(l_2 + l_3) \cdot y_A + (l_1 + l_3) \cdot y_B + (l_1 + l_2) \cdot y_C}{2 \cdot (l_1 + l_2 + l_3)} \quad (5.2)$$

The concept of the *Spieker center* can easily be generalized on polygons. We imagine the polygon is made from a wire of constant diameter. We look for its center of gravity; it is generally outside the wire. We consider a new polygon, constructed by k mass centers. Therefore it also has k vertices. We compute the *Point center* of the new polygon. The Point center of a r -gon is defined by the imagination that the masses are in the vertices of the polygon. Let $m_1, m_2, \dots, m_{r-1}, m_r$ be r masses. The polygon has the Point center $Point = (point_x, point_y)$.

$$point_x = \frac{1}{M} \cdot \sum_{i=1}^r m_i \cdot a_i \quad (5.3)$$

$$point_y = \frac{1}{M} \cdot \sum_{i=1}^r m_i \cdot b_i, \text{ and} \quad (5.4)$$

$$M = \sum_{i=1}^r m_i \text{ is the sum of the masses and} \quad (5.5)$$

$$(a_1, b_1), (a_2, b_2), \dots, (a_{r-1}, b_{r-1}), (a_r, b_r) \text{ are different vertices of the polygon.} \quad (5.6)$$

To calculate the Spieker center of a given simple polygon we have to consider a new polygon, constructed by k mass centers of the k edges. Therefore it also has k vertices. We assume that in the new polygon the masses are on these k vertices. The Spieker center of the given polygon is the Point center of the new polygon. The formulas are

$$spieker_x = \frac{1}{U} \cdot \sum_{i=1}^k l_i \cdot \left(\frac{1}{2} \cdot (x_i + x_{i+1}) \right) = \frac{1}{2 \cdot U} \cdot \sum_{i=2}^{k+1} (l_i + l_{i-1}) \cdot x_i \quad (5.7)$$

$$spieker_y = \frac{1}{U} \cdot \sum_{i=1}^k l_i \cdot \left(\frac{1}{2} \cdot (y_i + y_{i+1}) \right) = \frac{1}{2 \cdot U} \cdot \sum_{i=2}^{k+1} (l_i + l_{i-1}) \cdot y_i \quad (5.8)$$

$$\text{where } l_i = \sqrt{(x_i - x_{i+1})^2 + (y_i - y_{i+1})^2} \quad \text{and} \quad U = \sum_{i=1}^k l_i \quad (5.9)$$

We define $l_{k+1} := l_1$. Note the indices in the formulas! Note that it holds $(x_{k+1}, y_{k+1}) = (x_1, y_1)$. The variable ' l_i ' means the length of one edge of the polygon. Every edge $[(x_i, y_i), (x_{i+1}, y_{i+1})]$ has a center of gravity $\frac{1}{2} \cdot ((x_i, y_i) + (x_{i+1}, y_{i+1}))$. U is the perimeter of the polygon.

As an example we take the 5-gon of above. Its Spieker center is about $(0.50, 0.93)$. In exact coordinates it is

$$\left(\frac{1}{2}, \frac{1}{6 + 2 \cdot \sqrt{7}} \cdot \left(2 + 2 \cdot \sqrt{7} + \frac{1}{2} \cdot \sqrt{42} \right) \right) = \left(\frac{1}{2}, \sqrt{7} - 2 + \frac{1}{8} \cdot \left(3 \cdot \sqrt{42} - \sqrt{294} \right) \right). \quad (5.10)$$

Definition 5.1. Let us presume a simple polygon P . We call P *beautiful* if and only if it holds that B equals the Spieker center. We call P *perfect* if and only if all three centers are the same, i.e. it holds that B equals both $Cent$ and the Spieker center.

Lemma 5.2. Let s be a symmetry axis of a simple polygon P . The Spieker center is on the line $l(s) \cap Rectangle(P)$.

Proof. The segment s is a symmetry axis both for the entire polygon and for its contour. Therefore the Spieker center is on s . Because the Spieker center is the barycenter of the contour it has to be in $Rectangle(P)$. \square

Proposition 5.3. Let a simple polygon has two or more symmetry axes. Then it is perfect and all symmetry axis intersect in a single point.

Proof. The three points B , $Cent$ and the Spieker center all are on the line determined by a symmetry axis. There is only a single possibility that all points are on every symmetry axis. \square

Conjecture 5.4. In a simple polygon which is not a triangle we have that $B = Cent$ if and only if $B = Cent = Spieker$ center.

Conjecture 5.5. A triangle is perfect if and only if it is an equilateral triangle.

Conjecture 5.6. A r -gon is perfect if and only if it is an regular r -gon.

Conjecture 5.7. A simple polygon is beautiful if and only if it has more than one symmetry axis. In other words it holds that we have $B = Spieker$ center if and only if $B = Spieker$ center = $Cent$.

Acknowledgements: We thank Prof. Dr. Eberhard Oeljeklaus for a careful reading of the paper and for some advices and Rolf Baumgart for calculations

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