

Combination of evidence with different weighting factors a novel probabilistic-based dissimilarity measure approach[☆]

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Abstract: To solve the invalidation problem of Dempster-Shafer theory of evidence (DS) with high conflict in multi-sensor data fusion, this paper presents a novel combination approach of conflict evidence with different weighting factors using a new probabilistic dissimilarity measure. Firstly, an improved probabilistic transformation function is proposed to map basic belief assignments (BBAs) to probabilities. Then, a new dissimilarity measure integrating fuzzy nearness and introduced correlation coefficient is proposed to characterize not only the difference between basic belief functions (BBAs) but also the divergence degree of the hypothesis that two BBAs support. Finally, the weighting factors used to reassign conflicts on BBAs is developed and the Dempster's rule is choose to combine the discounted sources. Simple numerical examples are employed to demonstrate the merit of the proposed method. Through analysis and comparison of the results, the new combination approach can effectively solve the problem of conflict management with better convergence performance and robustness.

Keywords: Multi-sensor data fusion; Dempster-Shafer theory of evidence (DS); Dissimilarity measure; Discounting rule; Probability transformation

1. Introduction

Multisensor data fusion is a technology that combines information from several sources to form a unified picture^[1]. Dempster-Shafer (DS) theory of evidence is one of the most prevalent methods for data fusion and is firstly proposed by Dempster in the 1960s^[2] and further developed by Shafer in the 1970s^[3]. DS has been widely used in many regions, such as image processing^[4,5], target recognition and tracking^[6,7], fault diagnosis^[8], knowledge discovery^[9], to name a few. Unfortunately, in the framework of DS, the Dempster's rule, as an inherent problem, is incapable of managing the high conflicts from various information sources at the step of normalization and will generate counter-intuitive results as first highlighted by Zadeh^[10].

Since few years, a variety of combination methods have been proposed to achieve

effective data fusion on high degree of conflicting sources of evidence. By studying them, the overall methods can be summarized into two main categories: The first is to improve the rules of combination ^[11-13]. The representative methods are Lefevre's method^[11], Yager's method^[12], and so on. Scholars who put forward this method believe that the cause of high conflict evidence combination failure is due to some defects of the Dempster combination's rules; The second is to modify the original sources of evidence without changing the Dempster's combination rule ^[14--20]. The representative methods are Muphy's method^[14], Y. Deng's method^[15], Liu's method^[20], and so on. Our approach is based on the second kind of improvement way, for the improved combination rules can't meet the commutative law or associative law and the high conflict isn't due to Dempster's rule, the unreliable evidence is the real cause. The sources of evidence should be discounted according to the reliability. The basic idea of the discounting method is that if one source has great (small) dissimilarity with the others, its reliability should be low (high).

Therefore, the dissimilarity measure between two sources of evidence plays a crucial role in the discounting method. Jousselme et al ^[17] proposed a principled distance which regarded the evidence as the vector based on the geometry interpretation, but its computation burden is important. Liu ^[18] proposed the two-dimensional measure which consists of the Shafer's conflict coefficient and the pignistic probability distance between betting commitments. However, when one factor is large and another is small, the dissimilarity degree cannot be directly assured. Qu et al ^[19] proposed a conflict rate to proportion the conflict, but when the two pieces of evidence are equal, the conflict rate will cause a miscarriage of justice. Liu et al ^[20] proposed a dissimilarity measure to describe the divergences of two aspects between two pieces of evidence, the difference of beliefs and the difference of hypotheses which two pieces of evidence strongly support. But it is not good enough to capture the difference between BBAs in some cases as it will be seen. Based on the above analysis, the current methods are not adequate to precisely delineate the divergence between two pieces of evidence. This motivates researchers to develop a good and useful measure of dissimilarity.

In this study, a novel combination approach of conflict evidence is proposed. The novel dissimilarity measure is defined through integrating the fuzzy nearness and correlation coefficient by Hamacher T-conorm rule ^[22] based on an improved probabilistic transformation. The weighting factors adopted to discount the original sources are automatically determined according to the proposed probabilistic-based dissimilarity measure. The interest of our improved probabilistic transformation, the new dissimilarity measure and the discounted method to combine conflicting sources of evidence are illustrated through some numerical examples.

The rest of this paper is organized as follows: In Section 2, we briefly review the DS evidence theory. The new method for combining conflict evidence is proposed in Section 3. In Section 4, numerical examples are enumerated to show the performance of the existing alternatives and the proposed method. Section 5 concludes this paper.

2. Theory of evidence

2.1. Belief function

The frame of discernment, denoted by Θ , is a finite nonempty set including mutually exclusive and exhaustive elements. 2^Θ denotes the power set of composed with all the possible subsets of Θ . A basic belief assignment (BBA) is a function m mapping from 2^Θ to $[0, 1]$, and verifies the following conditions:

$$\begin{cases} m(\phi) = 0 \\ \sum_{A \subseteq \Theta} m(A) = 1 \end{cases} \quad (1)$$

where ϕ is the empty set. The subset A of Θ with nonzero masses are called the focal elements of m . There are also two other definitions in the theory of evidence. They are belief and plausibility functions associated with a BBA and are defined respectively as

$$Bel(A) = \sum_{B \subseteq A} m(B) \quad (2)$$

$$Pl(A) = \sum_{A \cap B \neq \phi} m(B) \quad (3)$$

$Bel(A)$ represents the total amount of probability that is allocated to A , while $Pl(A)$ can be interpreted as the amount of support that could be given to A . $Bel(A)$ and $Pl(A)$ are the lower and upper limit of the belief level of hypothesis A respectively.

2.2. Dempster's combination rule and the paradox problem

Suppose two bodies of evidence m_i and m_j are derived from two information sources, the Dempster's combination rule can be defined as

$$m(A) = m_i \oplus m_j = \begin{cases} \frac{\sum_{B \cap C = A} m_i(B)m_j(C)}{1 - K}, & A \neq \phi \\ 0, & A = \phi \end{cases} \quad (4)$$

$$K = \sum_{B \cap C = \phi} m_i(B)m_j(C) \quad (5)$$

where K is the conflict coefficient, reflecting the degree of conflict between the two bodies of evidence.

Note that, there are two limitations in applying DS evidence theory. One is that the counter-intuitive results can be generated when high conflicting evidence are infused using Dempster's rule as shown in classical Zadeh's example^[10]. The second is that the conflict coefficient is not very appropriate to really characterize the conflict between BBAs, particularly in case of two equal BBAs as reported in [18,21].

Example 1 (Zadeh's example). Assume m_1 and m_2 over $\Theta = \{\theta_1, \theta_2, \theta_3\}$ are defined as:

$$\begin{aligned} m_1 : m_1(\theta_1) = 0.9, m_1(\theta_2) = 0.1, m_1(\theta_3) = 0 ; \\ m_2 : m_2(\theta_1) = 0, m_2(\theta_2) = 0.1, m_2(\theta_3) = 0.9. \end{aligned}$$

According to Eq.(4) and Eq.(5), we get: $m(\theta_1) = m(\theta_3) = 0, m(\theta_2) = 1$ and $K = 0.99$. We can see that m_1 and m_2 have low support level to hypothesis θ_2 , but the resulting structure has complete support to θ_2 . This appears to be counter-intuitive.

Example 2. Consider two equal m_1 and m_2 over $\Theta = \{\theta_1, \theta_2, \theta_3, \theta_4\}$ are defined as:

$$\begin{aligned} m_1 : m_1(\theta_1) &= m_1(\theta_2) = m_1(\theta_3) = m_1(\theta_4) = 0.25 ; \\ m_2 : m_2(\theta_1) &= m_2(\theta_2) = m_2(\theta_3) = m_2(\theta_4) = 0.25. \end{aligned}$$

According to Eq.(5), we get: $K = 0.75$. This reveals that the two pieces of evidence are high degree of conflict, but in fact they are equal.

2.3. Pignistic transformation

When working in the probabilistic framework, the focal elements are singletons and exclusive, and the degree of the conflict become easier to compute regardless the intrinsic relationship between BBAs. Probabilistic transformation is a useful tool to map BBAs to probabilities. A classical transformation is the pignistic transformation^[24], defined as

$$BetP_m(\theta_i) = \sum_{A \subseteq \Theta, \theta_i \in A} \frac{1}{|A|} m(A) \quad (6)$$

where $|A|$ is the number of elements in subset A . $BetP_m$ transfers the positive mass of belief of each non-specific element onto the singletons involved in that element according to the cardinal number of the proposition.

3. A novel combination approach of conflict evidence

The fundamental goal of our approach is to allocate reasonable weighting factors to the evidence, and make a much better combination. The derivation of the weights of the sources is based on the widely well-adopted principle that *the truth lies in the majority opinion*. The sources which are highly conflicting with the majority of other sources will be automatically assigned with a very low weighting factor in order to decrease their bad influence in the fusion process. To determining the weighting factors, the conflict should be well measured first.

The degree of conflict between BBAs has been measured in many works, including conflict coefficient K ^[3], Jousselme's distance measure d_j ^[17], pignistic probability distance $difBetP$ ^[18], conflict rate λ ^[19] and dissimilarity measure $DismP$ ^[20]. **These measures** cannot characterize the conflict comprehensively and accurately. What's more, the distance measures^[17,18,20] are based on the pignistic transformation^[23], **but such transformation is only a simple average in mathematics**. It considers the role of belief functions **while ignoring** the effect of the plausibility functions. Therefore, we propose an improved probabilistic transformation to transform BBAs into probabilities to overcome the shortcomings of pignistic transformation. Then based on the improved probabilistic transformation method, a novel dissimilarity degree which integrates the fuzzy nearness and correlation coefficient by Hamacher T-conorm rule is proposed.

3.1 An improved probabilistic transformation

Definition 1. By utilizing the information contained in the belief function and plausibility function of the propositions in the DS, a new method for transforming BBA into probability is defined as

$$P(\theta_i) = Bel(\theta_i) + \frac{BEL \cdot Bel(\theta_i) + (1 - BEL)Pl(\theta_i)}{\sum_{\theta_j \in \Theta} BEL \cdot Bel(\theta_j) + (1 - BEL)Pl(\theta_j)} (1 - BEL) \quad (7)$$

where BEL is the total value of belief functions, defined as $BEL = \sum Bel(\theta_i)$. The uncertain information that can be reallocated can be represented as $1 - BEL$. BEL can well balance the degree of influence of the the belief function and plausibility function. If the value of BEL is big, the certainty information plays a dominant role, so the influence of Bel should be bigger than Pl . On the contrary, if the value of $1 - BEL$ is big, the proportion of uncertain information is larger than the certainty information, so the influence of Pl should be bigger than Bel .

The improved probabilistic transform function satisfies $P(\theta_i) \in [0,1]$ and $\sum P(\theta_i) = 1$. It's worthy of noting that the presented probabilistic transformation not only includes the special cases described in [24] and [25], but also can well transform the BBAs into probabilities in general conditions:

- 1) If $BEL = 1$, all the focal elements are single sets, and so the BBAs should remain unchanged. The (7) can be simplified to $P(\theta_i) = Bel(\theta_i)$.
- 2) If $BEL = 0.5$, Bel and Pl have the same influence on the allocations of the uncertain information, the (7) degrades into the probabilistic transform function

proposed in [24], described as $P(\theta_i) = Bel(\theta_i) + \frac{Bel(\theta_i) + Pl(\theta_i)}{\sum_{\theta_j \in \Theta} Bel(\theta_j) + Pl(\theta_j)} (1 - BEL)$.

- 3) If $BEL = 0$, all the focal elements are multiple sets and the allocating of the uncertain information is only based on the Pl , so the (7) degrades into the plausibility function-based transform (PFT) proposed by Cobb and Shenoy in [25], described as

$$P(\theta_i) = \frac{Pl(\theta_i)}{\sum Pl(\theta_i)}$$

Example 3. Let the BBA over the same frame of discernment $\Theta = \{\theta_1, \theta_2, \theta_3\}$ be as follows:

$$\begin{aligned} m : m_1(\theta_1) &= 0.4, m_1(\theta_2) = 0.2, m_1(\theta_3) = 0.1, \\ m_1\{\theta_1, \theta_2\} &= 0.2, m_1(\Theta) = 0.1. \end{aligned}$$

In example 3, $BEL = 0.7$. We choose Shannon entropy $H(x) = -\sum p(x) \log_2 p(x)$ to measure the uncertainty of the probabilities after transformation. The results of probabilities and uncertainties in such general case are listed in Table 1. By analysis the results, the improved probability transformation can get more effective probability and the smallest information uncertainty than the methods proposed in [23], [24] and [25], since it

Table 1. The results of probabilistic transformation in example 3

	θ_1	θ_2	θ_3	$H(x)$
$BetP_m(\theta_i)$ [23]	0.5333	0.3333	0.1333	0.4213
PT[24]	0.5435	0.2913	0.1652	0.4291
PFT[25]	0.5000	0.3571	0.1429	0.4310
$P(\theta_i)$	0.5615	0.2956	0.1429	0.4179

balances the influence of belief function and plausibility function well with the factor BEL .

3.2 The new dissimilarity measure

3.2.1 Fuzzy nearness

Fuzzy set theory is specially designed to provide a language with syntax and semantics to translate qualitative judgments into numerical reasoning and to capture subjective and vague uncertainty. In this theory, fuzzy nearness is used to measure the lever of similarity between two objects. In this work, we use the fuzzy nearness^[26] to measure the similarity between BBAs. We use the fuzzy nearness^[26] to measure the similarity between BBAs. The most commonly used fuzzy nearness is the well known maximum-minimum method. The merit of fuzzy nearness will be illustrated in example 4 by comparing with the distance measure ^[17, 18, 20].

Definition 2. Assume we have got a sequence of n pieces of probability evidence $\{P_1, P_2, \dots, P_n\}$ rebuilt by the improved probabilistic transformation form $\{m_1, m_2, \dots, m_n\}$. The level of similarity between two BBAs can be calculated by

$$R(m_i, m_j) = \frac{\sum_{k=1}^n (P_i(\theta_k) \wedge P_j(\theta_k))}{\sum_{k=1}^n (P_i(\theta_k) \vee P_j(\theta_k))} \quad i, j = 1, 2, \dots, m \quad (8)$$

where \wedge and \vee is the operators for calculating the minimum and maximum respectively. The fuzzy nearness satisfies $R(m_i, m_j) \in [0, 1]$. In the example 1 and example 2, according to (9), we get $R(m_1, m_2) = 0.0526$ and $R(m_1, m_2) = 1$ respectively, which means that the fuzzy nearness can well reflect the difference between two highly conflict BBAs or two equal BBAs.

Example 4. Let's consider the frame $\Theta = \{\theta_1, \theta_2, \theta_3\}$ and the following three independent BBAs over the same frame of discernment be as follows:

$$\begin{aligned} m_1 : m_1(\theta_1) &= 0.5, m_1(\theta_2) = 0.3, m_1(\theta_3) = m_1(\Theta) = 0.1; \\ m_2 : m_2(\theta_1) &= 0.8, m_2(\theta_2) = 0.1, m_2(\theta_3) = 0.1; \\ m_3 : m_3(\theta_1) &= 0.3, m_3(\theta_2) = 0.5, m_3(\Theta) = 0.2. \end{aligned}$$

one gets:

$$\begin{aligned}
d_J(\mathbf{m}_1, \mathbf{m}_2) &= 0.2582, & d_J(\mathbf{m}_1, \mathbf{m}_3) &= 0.2160; \\
difBetP(\mathbf{m}_1, \mathbf{m}_2) &= 0.2667, & difBetP(\mathbf{m}_1, \mathbf{m}_3) &= 0.2333; \\
DistP(\mathbf{m}_1, \mathbf{m}_2) &= 0.2667, & DistP(\mathbf{m}_1, \mathbf{m}_3) &= 0.2333; \\
R(\mathbf{m}_1, \mathbf{m}_2) &= 0.6062, & R(\mathbf{m}_1, \mathbf{m}_3) &= 0.5576.
\end{aligned}$$

The dissimilarity between \mathbf{m}_1 and \mathbf{m}_2 are larger than that between \mathbf{m}_1 and \mathbf{m}_3 according to the distance measures $d_J^{[17]}$, $difBetP^{[18]}$, and $DistP^{[20]}$, which are counter-intuitive. The fuzzy nearness $R(\mathbf{m}_1, \mathbf{m}_2) > R(\mathbf{m}_1, \mathbf{m}_3)$ shows \mathbf{m}_1 and \mathbf{m}_2 are more similar than \mathbf{m}_1 and \mathbf{m}_3 , which is inline with the intuitive judgment. This illustrates the fuzzy nearness can measure the conflict in the case that the distance measures fails.

However, the fuzzy nearness is not stable. If $\mathbf{m}'_2 : \mathbf{m}'_2(\theta_1) = 0.8, \mathbf{m}'_2(\theta_3) = 0.2$ is used to instead of \mathbf{m}_2 in example 4, one gets $R(\mathbf{m}_1, \mathbf{m}'_2) = 0.4999, R(\mathbf{m}_1, \mathbf{m}_3) = 0.5576$. In this case, the fuzzy nearness can not work well. Because the degree of the divergence between the distinct hypotheses strongly supported by each source must play an important role^[18].

3.2.2 correlation coefficient

A conflict between two BBAs can be interpreted qualitatively as the fact that one source strongly supports one hypothesis and the other strongly supports another hypothesis, and the two hypotheses are not compatible (their intersection is empty) ^[20]. This is intuitively consistent, and will be adopted here. [20] defined a conflict coefficient to reflect the divergence degree by the pair of maximal subjective probability from conflict sources, but it cannot reflect the difference between two non-conflicting sources of evidence. In this part, a correlation coefficient is proposed to reflect the the divergence degree of the hypothesis that two belief functions strongly support based on the new proposed probabilistic transformation. The proposed correlation coefficient can reflect the difference of two conflicting or non-conflicting sources of evidence.

Definition 3. Let P_i and P_j be two pieces of probability evidence produced by the improved probabilistic transformation on the frame Θ . The correlation coefficient is defined by

$$CoC(\mathbf{m}_i, \mathbf{m}_j) = \begin{cases} \frac{P_i(\theta_{\max}^{P_i}) + P_j(\theta_{\max}^{P_j})}{2}, & \text{if } \theta_{\max}^{P_i} = \theta_{\max}^{P_j} \\ \frac{P_i(\theta_{\min}^{P_i}) + P_j(\theta_{\min}^{P_j})}{2}, & \text{if } \theta_{\max}^{P_i} \neq \theta_{\max}^{P_j} \end{cases} \quad (9)$$

where $\theta_{\max}^{P_i} = \operatorname{argmax}_{\theta} P_i(\theta)$, $\theta_{\min}^{P_i} = \operatorname{argmin}_{\theta} P_i(\theta)$. The correlation coefficient is defined by using the maximal approximate subjective probability of the BBAs. If two sources of evidence distribute most of their mass of belief to the same elements, the similarity between the two sources in such conditions is calculated by the average of maximal probability. Otherwise, the amount of conflict will be represented by the product of the average of minimal subjective probability. So our definition can well describe the difference of two conflicting or non-conflicting sources of evidence.

In the example 4, one get $CoC(\mathbf{m}_1, \mathbf{m}'_2) = 0.7689, CoC(\mathbf{m}_1, \mathbf{m}_3) = 0.05$, which indicates that the correlation coefficient can well reflects the divergence of incompatible hypotheses that two sources of evidence commit most of their beliefs to.

However, according to the definition of the correlation coefficient, it only considers the elements that two sources of evidence strongly support and ignores the other elements of BBAs. Actually, the fuzzy nearness and correlation coefficient are complementary and they separately capture different aspects of the dissimilarity of BBA's.

3.2.3 The new similarity measure

Taking into account both them in the elaboration of a new measure of dissimilarity seems therefore a natural way to capture two aspects of the dissimilarity of BBAs. Consider the analysis in [20], Hamacher T-conorm fusion rule^[22] satisfies important properties and also will be used here.

Definition 4. Based on the improved probabilistic transformation, the new dissimilarity measure denoted as Sim is defined by fusing fuzzy nearness and correlation coefficient, described as:

$$Sim(\mathbf{m}_i, \mathbf{m}_j) = \frac{R(\mathbf{m}_i, \mathbf{m}_j) + CoC(\mathbf{m}_i, \mathbf{m}_j)}{1 + R(\mathbf{m}_i, \mathbf{m}_j) \times CoC(\mathbf{m}_i, \mathbf{m}_j)} \quad (10)$$

In order to verify the effectiveness of the new dissimilarity measure, the example 5 dawn form [18] is conducted to compare it with the methods proposed in [3,17,18,19,20]. Since the compared methods are proportional to the conflict and our method is inversely proportional to the conflict, with the purpose of making an intuitive comparison, we define a variable $DisSim$, denoted as

$$DisSim(\mathbf{m}_i, \mathbf{m}_j) = 1 - Sim(\mathbf{m}_i, \mathbf{m}_j) \quad (11)$$

Example 5. Let Θ be a frame of discernment with 20 elements in Shfer's model. We denote θ_i with its subscript i and the two BBAs are defined as follows:

$$\begin{aligned} \mathbf{m}_1 : m_1(2,3,4) = 0.05, m_1(7) = 0.05, m_1(\Theta) = 0.1, m_1(A) = 0.8; \\ \mathbf{m}_2 : m_2(1,2,3,4,5) = 1. \end{aligned}$$

where A is the subset of Θ . The number of elements in A is increased step by step from 1 to 20. Consequently, there are 20 cases in this example. The results of the dissimilarity measures between \mathbf{m}_1 and \mathbf{m}_2 is graphically illustrated in Fig.1.

From Fig. 1, it can be seen that although the novel dissimilarity measure $DisSim$ presents a similar behavior with the $difBetP$, d_j and $DismP$, our function $DisSim$ more slowly than the existing ones. The value of conflict coefficient K is always equal to 0.05 whether the size of subset A changes or not. λ indicates that \mathbf{m}_1 and \mathbf{m}_2 are totally different except for case 5, so it can't distinguish the variation among these cases.

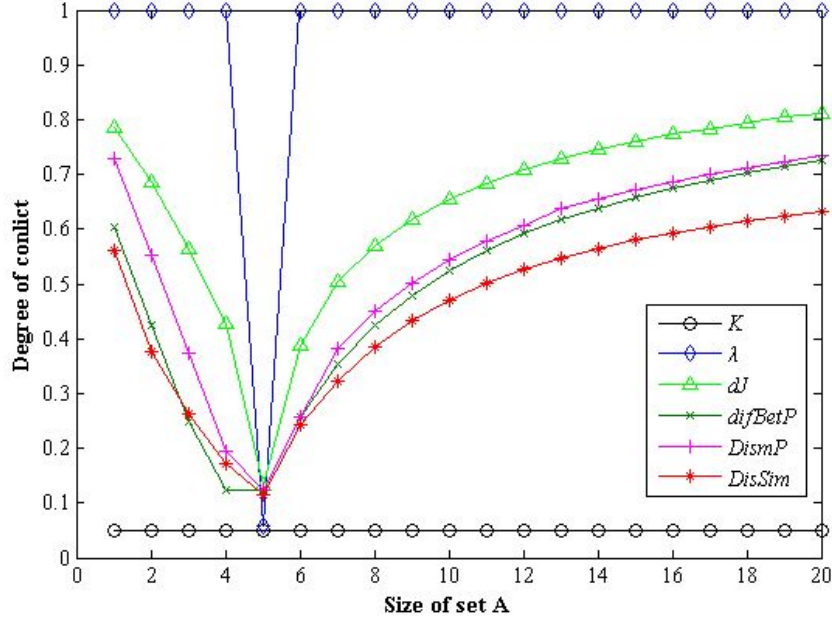


Fig 1. Comparisons of different conflict measure methods when subsets A changes in example 5. In case 4 and case 5, the $difBetP$ is equal, but the two pieces of evidence have obvious difference. It's worthy to mentioning that, when m_1 becomes more and more uncertain, all singletons get small probability gain through the probabilistic transformation. The divergence degree, reflecting the strong support of sources in different hypotheses, is becoming lower and lower. Therefore, the new dissimilarity measure can well reflect the conflict between two sources of evidence and is more relational than other measures.

3.3 Combination based on discounting evidence

Suppose the number of sources of evidence is n . The evidence similarity can be represented with matrix S :

$$S = \begin{cases} Sim(\mathbf{m}_i, \mathbf{m}_j) & i \neq j \\ 1 & i = j \end{cases} \quad i, j = 1, 2, \dots, n \quad (12)$$

The support degree all sources of evidence to evidence j is can be defined by:

$$Sup(\mathbf{m}_j) = \sum_{j=1, j \neq i}^n Sim(\mathbf{m}_i, \mathbf{m}_j) \quad i, j = 1, 2, \dots, n \quad (13)$$

The credibility of evidence can be calculated by the following formula:

$$c(\mathbf{m}_i) = Sup(\mathbf{m}_i) / \sum_{k=1}^n Sup(\mathbf{m}_k) \quad (14)$$

The weight of evidence is defined by:

$$\omega_i = c(\mathbf{m}_i) / \max_{1 \leq k \leq n} (c(\mathbf{m}_k)) \quad (15)$$

Definition 5. Let $\Theta = \{\theta_1, \theta_2, \dots, \theta_m\}$ be the frame of discernment, there are n evidence participating in combination, respectively are $\mathbf{m}_1, \mathbf{m}_2, \dots, \mathbf{m}_n$. Let the weight of \mathbf{m}_i be ω_i , we discount the evidence by the weighting factor as follow formula [3]:

$$\mathbf{m}'_i(\theta) = \begin{cases} \omega_i \times \mathbf{m}(\theta), & \forall \theta \in \Theta, \theta \neq \phi \\ 1 - \omega_i + \omega_i \times \mathbf{m}(\theta), & \theta = \Theta \end{cases} \quad (16)$$

then do the combination of the discounted evidence by the Dempster's rule:

$$m(\theta) = m'_1(\theta) \oplus m'_2(\theta) \oplus \dots \oplus m'_n(\theta) \quad (17)$$

4. Numerical examples

A typical architecture of the proposed combination method is shown in Fig. 2. It consists of two main parts: determination of belief functions and combination of the sources of evidence. The construction of BBAs can be processed by the existing belief function generators and are out of the scope of this paper. With the obtained sources of evidence, the proposed approach is employed to measure the degree of conflict of BBAs and combine highly conflicting sources of evidence with weighting factors for decision making. Three simple examples are employed to show the performance of the proposed approach with respect to other methods, including DS[3], Yager's rule^[12], Murphy's method^[14], Y.Deng's method^[15] and Liu's method^[20].

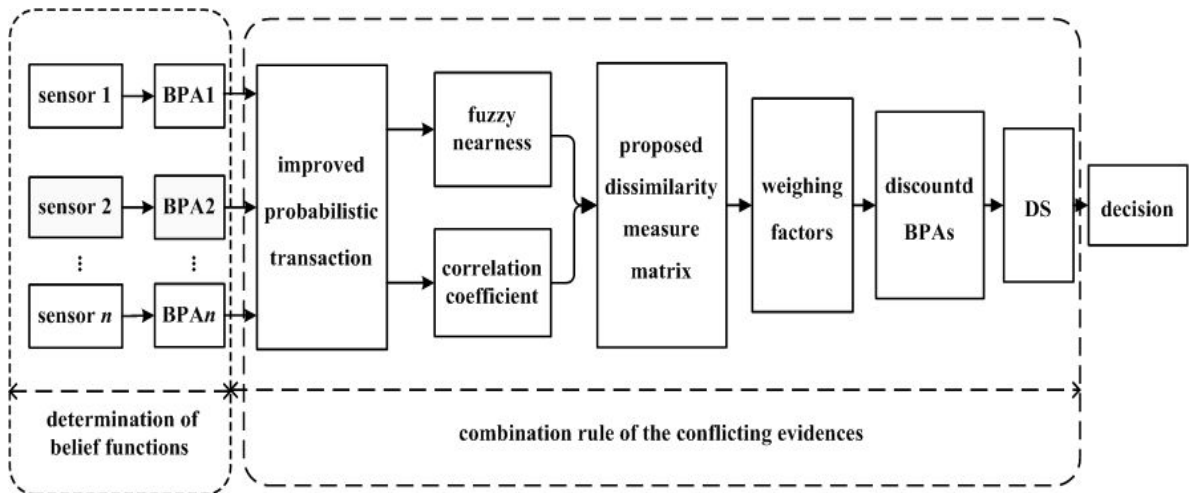


Fig 2. The typical architecture of the proposed combination scheme

4.1. Feasibility

The classic Zadeh's example is used in this part to illustrate that the proposed approach can solve the invalidation problem of DS combination rule with high conflict. The combined results are tabulated are listed in Table 2.

Table 2. Combination results of m_1 and m_2 for example 1

Methods	$m(\theta_1)$	$m(\theta_2)$	$m(\theta_3)$	$m(\theta)$
DS ^[3]	0	1	0	0
Our results	0.3691	0.0919	0.3691	0.1699

From Table 2, we can obtain that, DS rule^[3] assigns 100% certainty to the minority belief hypothesis θ_2 , which is counter-intuitive. The proposed methods can balance the conflict and allocate the same belief 0.3691 to θ_1 and θ_3 , and 0.1699 to the unknown proposition. Moreover, when a new source of evidence m_3 supporting θ_1 is collected and then combined, the proposed approach confirm θ_1 to 0.6772 while DS rule

constantly assign the 100% certainty to θ_2 . What's more, the belief allocated to the unknown proposition drops to 0.1217. The new source of evidence and combined results are listed in Table 3. This illustrates that our approach can well combine highly conflicting sources of evidence with a correct decision.

Table 3. The new source of evidence m_3 and combined results

	$m(\theta_1)$	$m(\theta_2)$	$m(\theta_3)$	$m(\Theta)$
m_3	0.9	0.1	0	0
DS ^[3]	0	1	0	0
Our results	0.6772	0.0716	0.1301	0.1217

4.2. Robustness

In the real application decision-making support systems, the interference of surroundings or the aberrant measurement of sensors, always lead to the varying of the collected belief functions within a certain range. Therefore, the robustness of the combination method directly affect the synthesis results.

Example 6 (employed from reference [20]). Let's consider three simple Bayesian BBAs over the frame $\Theta = \{\theta_1, \theta_2, \theta_3\}$ as in Table 4. The source of evidence No.3 can provide two similar BBAs denoted m_{3A} and m_{3B} . Let's see how the small difference affects the fusion results.

Table 4. Four sources of evidence in example 6

	θ_1	θ_2	θ_3
m_1	0	0.9	0.1
m_2	0.6	0.25	0.15
m_{3A}	0.75	0.15	0.1
m_{3B}	0.7	0.2	0.1

From Table 4, we can see that m_2 , m_{3A} and m_{3B} commit most belief on θ_1 , whereas m_1 distributes the largest belief to θ_2 . Thus, m_1 won't be considered as reliable as the other ones. The combination results of different methods are shown in the Table 5.

Table 5. Combination results of different methods in example 6

Methods	$m_{123A}(\theta_1)$	$m_{123B}(\theta_1)$	$m_{123A}(\theta_2)$	$m_{123B}(\theta_2)$	$m_{123A}(\theta_3)$	$m_{123B}(\theta_3)$
DS ^[3]	0.0000	0.0000	0.9574	0.9677	0.0426	0.0323
Yager ^[12]	0.5700	0.5320	0.1478	0.197	0.0775	0.0775
Murphy ^[14]	0.5235	0.4674	0.4674	0.5235	0.0091	0.0091
Y.Deng ^[15]	0.7264	0.6823	0.2502	0.2968	0.0234	0.0209
Liu ^[20]	0.8332	0.7958	0.1454	0.1829	0.0214	0.0213
Our results	0.8837	0.8513	0.0931	0.1159	0.0232	0.0327

The fusion results in Tables 5 show that m_{123A} and m_{123B} are very similar. DS rule provides the unreasonable result that θ_1 is impossible to happen. Although Yager's rule has a preferable robustness, the outcome is poor since it assigns the conflict to the unknown domain. In the **Murphy's method**, m_{123A} considers that θ_1 is most likely to be true, whereas m_{123B} believes that θ_2 should correspond to the truth, **therefore** they lead to opposite conclusion. This indicated that average BBAs method is not robust enough. Once the discounting approach in [15], [20] and this paper is applied, one get the largest mass of belief to θ_1 as expected. Moreover, if our method is used as the dissimilarity coupled with the proposed method of weighting factors determination, it can produce the most specific and robust results. This illustrates that the proposed method can work well with perfect robustness even in high conflicting cases.

4.3. Effectiveness

In this section, a synthetic numerical example of a simulation of the multi-sensor based automatic target recognition system is employed to analyze the effectiveness of the proposed approach of combination.

Example 7. Let the frame of target discernment is $\Theta = \{\theta_1, \theta_2, \theta_3\}$ and the real target is θ_1 . From five distinct information sources the system has collected seven singleton bodies of evidence m_1 , m_2 , m_3 , m_4 and m_5 , including the conflicting evidence m_3 from the non-reliable information source, shown as Table 6.

Table 6. The collected sources of evidence of the target recognition system

	θ_1	θ_2	θ_3	$\{\theta_1, \theta_2\}$	$\{\theta_2, \theta_3\}$	Θ
m_1	0.8	0.1	0	0	0	0.1
m_2	0.5	0.2	0.1	0.2	0	0
m_3	0	0.9	0.1	0	0	0
m_4	0.5	0.1	0.1	0.1	0	0.2
m_5	0.6	0.1	0	0	0.1	0.2

In Table 6, m_1 , m_2 , m_4 and m_5 assign most of their belief to θ_1 , but m_3 oppositely commits its largest mass of belief to θ_2 . m_3 is considered as the least reliable source. The sources of evidences are **firstly** transferred into probabilities by the proposed probability transformation. **Then the weighting factors are determined by the new probability-based dissimilarity measure.** All the combined results of the discounted sources of evidence are listed in Table 7 and the belief assignment to the target θ_1 of the different alternatives are graphically illustrated in Fig. 3.

As can be observed in the Table 7, the **Dempster** combination rule concludes that the target θ_1 is very unlikely to happen whereas θ_2 is almost sure to happen. Such unexpected behavior shows that DS rule is risky to be used to combine sources of evidence in a high conflicting situation. The results of **Yager's rule**^[12] indicates that θ_1 has a small mass of belief after the conflict evidence m_3 arrives, since it allocates the

Table 7. Combination results of different methods of the target recognition system

Methods	m_{12}	m_{123}	m_{1234}	m_{12345}
DS ^[3]	$m(\theta_1)=0.8714$			
	$m(\theta_2)=0.0857$	$m(\theta_2)=0.9863$	$m(\theta_2)=0.9897$	$m(\theta_2)=0.9922$
	$m(\theta_3)=0.0143$	$m(\theta_3)=0.0137$	$m(\theta_3)=0.0013$	$m(\theta_3)=0.0078$
Yager ^[12]	$m(\theta_1, \theta_2)=0.0286$			
	$m(\theta_1)=0.6514$		$m(\theta_1)=0.1769$	$m(\theta_1)=0.3157$
	$m(\theta_2)=0.0592$	$m(\theta_2)=0.3203$	$m(\theta_2)=0.2450$	$m(\theta_2)=0.2146$
	$m(\theta_3)=0.0102$	$m(\theta_3)=0.0855$	$m(\theta_3)=0.1561$	$m(\theta_3)=0.0715$
	$m(\theta_1, \theta_2)=0.0201$	$m(\Theta)=0.6842$	$m(\theta_1, \theta_2)=0.1326$	$m(\theta_1, \theta_2)=0.0349$
	$m(\Theta)=0.2591$		$m(\Theta)=0.2894$	$m(\theta_2, \theta_3)=0.0348$
Murphy ^[14]				$m(\Theta)=0.3285$
	$m(\theta_1)=0.8136$	$m(\theta_1)=0.5347$	$m(\theta_1)=0.6453$	$m(\theta_1)=0.7169$
	$m(\theta_2)=0.1144$	$m(\theta_2)=0.4582$	$m(\theta_2)=0.3493$	$m(\theta_2)=0.2809$
	$m(\theta_3)=0.0305$	$m(\theta_3)=0.0035$	$m(\theta_3)=0.0026$	$m(\theta_3)=0.0014$
	$m(\theta_1, \theta_2)=0.0380$	$m(\theta_1, \theta_2)=0.0035$	$m(\theta_1, \theta_2)=0.0026$	$m(\theta_1, \theta_2)=0.0006$
Y.Deng ^[15]	$m(\Theta)=0.0035$	$m(\Theta)=0.0001$	$m(\Theta)=0.0002$	$m(\theta_2, \theta_3)=0.0001$
				$m(\Theta)=0.0001$
	$m(\theta_1)=0.7836$	$m(\theta_1)=0.6728$	$m(\theta_1)=0.7364$	$m(\theta_1)=0.8102$
	$m(\theta_2)=0.1087$	$m(\theta_2)=0.2492$	$m(\theta_2)=0.2247$	$m(\theta_2)=0.1727$
	$m(\theta_3)=0.0181$	$m(\theta_3)=0.0152$	$m(\theta_3)=0.0137$	$m(\theta_3)=0.0010$
Liu ^[20]	$m(\theta_1, \theta_2)=0.0892$	$m(\theta_1, \theta_2)=0.0628$	$m(\theta_1, \theta_2)=0.0252$	$m(\theta_1, \theta_2)=0.0161$
	$m(\theta_1)=0.7908$	$m(\theta_1)=0.7621$	$m(\theta_1)=0.8355$	$m(\theta_1)=0.8873$
	$m(\theta_2)=0.1099$	$m(\theta_2)=0.1414$	$m(\theta_2)=0.1003$	$m(\theta_2)=0.0905$
	$m(\theta_3)=0.0323$	$m(\theta_3)=0.0319$	$m(\theta_3)=0.0248$	$m(\theta_3)=0.0082$
	$m(\theta_1, \theta_2)=0.0645$	$m(\theta_1, \theta_2)=0.0622$	$m(\theta_1, \theta_2)=0.0386$	$m(\theta_1, \theta_2)=0.0136$
Our results	$m(\Theta)=0.0025$	$m(\Theta)=0.0024$	$m(\Theta)=0.0008$	$m(\theta_2, \theta_3)=0.0002$
				$m(\Theta)=0.0002$
	$m(\theta_1)=0.8865$	$m(\theta_1)=0.8461$	$m(\theta_1)=0.9299$	$m(\theta_1)=0.9675$
	$m(\theta_2)=0.0771$	$m(\theta_2)=0.1082$	$m(\theta_2)=0.0517$	$m(\theta_2)=0.0280$
	$m(\theta_3)=0.0151$	$m(\theta_3)=0.0151$	$m(\theta_3)=0.0062$	$m(\theta_3)=0.0025$
			$m(\theta_1, \theta_2)=0.0018$	
	$m(\theta_1, \theta_2)=0.0201$	$m(\theta_1, \theta_2)=0.0119$	$m(\theta_1, \theta_2)=0.0018$	
	$m(\Theta)=0.0012$	$m(\Theta)=0.0012$	$m(\Theta)=0.0003$	$m(\theta_2, \theta_3)=0.0001$
			$m(\Theta)=0.0001$	

majority of the belief to the unknown domain Θ . This reflects that the Yager's rule is impossible to make an accurate decision. In Murphy's method^[14], although θ_1 has a higher mass of belief than θ_2 as expected, the results are only the average of the BBAs. Y.Deng's method^[15], Liu's method^[20] and the proposed approach can generate right results, because once the discounting method is applied, the conflict evidence m_3 becomes strongly discounted owing to its largest conflict with other sources. From Fig.3, one sees that the proposed probabilistic-based dissimilarity measure coupled with the

automatic discounting factors determination generates more effective results with a better convergence performance than all other methods .

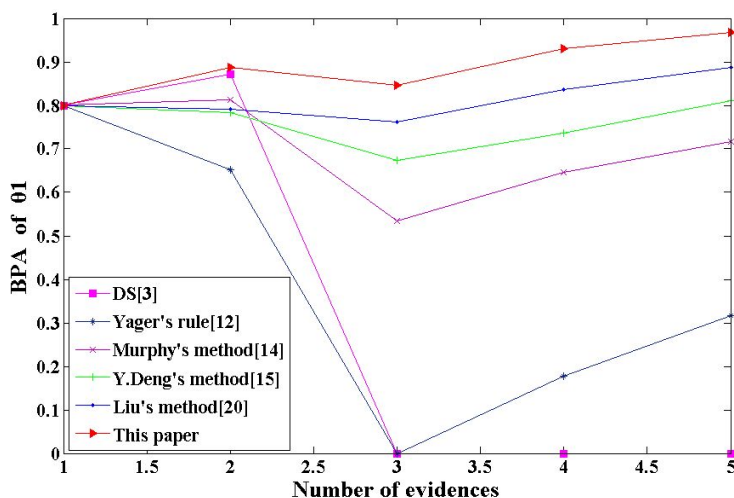


Fig 3. The belief assignment allocated to target θ_1 of different alternatives

5. Conclusions

In this paper, a new method has been proposed to combine conflict sources of evidence with different weighting factors. The merit of the new method proposed in this work lies in the elaboration of an efficient probability transformation and a comprehensively probabilistic-based dissimilarity measure which can be used for the determination of the weighting factors of the sources involved in the fusion process. Through aforementioned analysis and comparison, the proposed approach can effectively solve the counter-intuitive behaviors of the classical DS rule in combining highly conflicting sources. Furthermore, it can make the right decision with better robustness and effectiveness performance for the decision-making support system or target detection system.

Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

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